



(12) **United States Patent**  
**Bonutti et al.**

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(54) **RANGE OF MOTION DEVICE**

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**Related U.S. Application Data**

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(Continued)

(51) **Int. Cl.**  
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**A61H 1/02** (2006.01)  
**A61F 5/01** (2006.01)

(52) **U.S. Cl.**  
CPC ..... **A61H 1/024** (2013.01); **A61F 5/0102** (2013.01); **A61H 1/008** (2013.01); **A61H 1/02** (2013.01);

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(58) **Field of Classification Search**

CPC ..... A61F 2002/2839; A61F 2002/30062;  
A61F 2002/30075; A61F 2002/30224; A61F  
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2230/0069; A61F 2240/001; A61F 2250/001  
USPC ..... 602/20–28; 128/878–879, 882  
See application file for complete search history.

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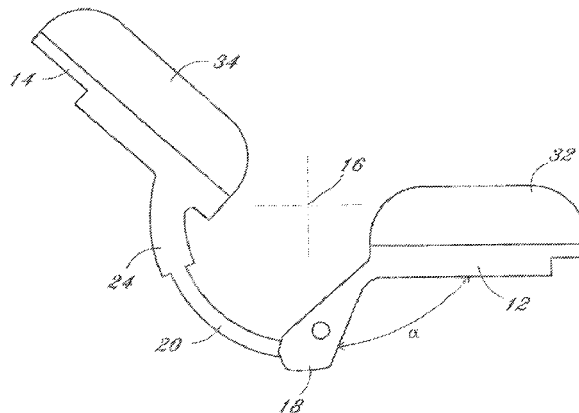
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(57) **ABSTRACT**

A device for moving a knee joint in a body of a patient is provided. The device includes a first arm member coupled to a first leg support configured to support an upper portion of a leg of the patient, a second arm member coupled to a second leg support configured to support at least one of a lower portion of a leg and a foot of the patient, and a control assembly operatively connected to the first and second arm members and configured to selectively move the second arm member relative to the first arm member. The control assembly includes a first motorized drive assembly coupled to the first and second arm members and operable to drive movement of the second arm member relative to the first arm member and a second motorized drive assembly coupled to the first and second arm members and operable to drive movement of the second arm member relative to the first arm member.

**24 Claims, 30 Drawing Sheets**



**Related U.S. Application Data**

13/151,962, filed on Jun. 2, 2011, now Pat. No. 8,206,329, which is a continuation of application No. 12/272,436, filed on Nov. 17, 2008, now Pat. No. 7,981,067, which is a continuation of application No. 11/533,839, filed on Sep. 21, 2006, now Pat. No. 7,452,342, which is a continuation-in-part of application No. 11/261,424, filed on Oct. 28, 2005, now Pat. No. 8,066,656, which is a continuation-in-part of application No. 10/795,892, filed on Mar. 8, 2004, now Pat. No. 7,112,179.

**(52) U.S. Cl.**

CPC ..... *A61H 1/0266* (2013.01); *A61F 2005/0139* (2013.01); *A61H 1/0244* (2013.01); *A61H 1/0277* (2013.01); *A61H 1/0281* (2013.01); *A61H 1/0285* (2013.01); *A61H 2001/0207* (2013.01); *A61H 2001/027* (2013.01); *A61H 2203/00* (2013.01)

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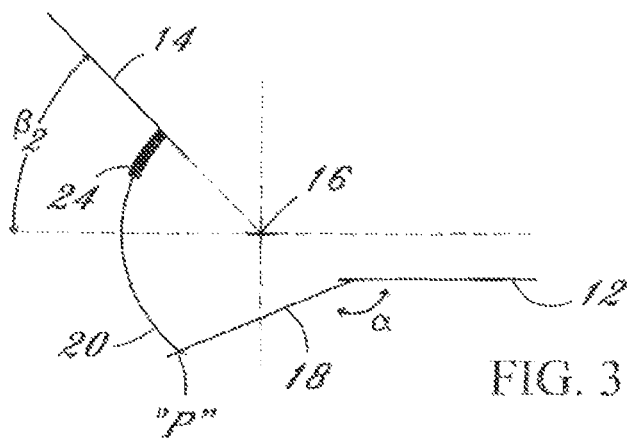
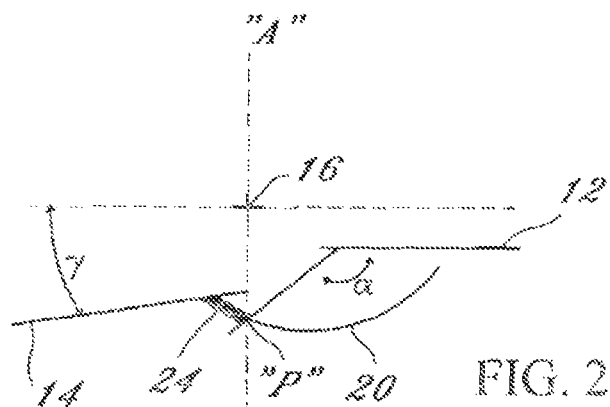
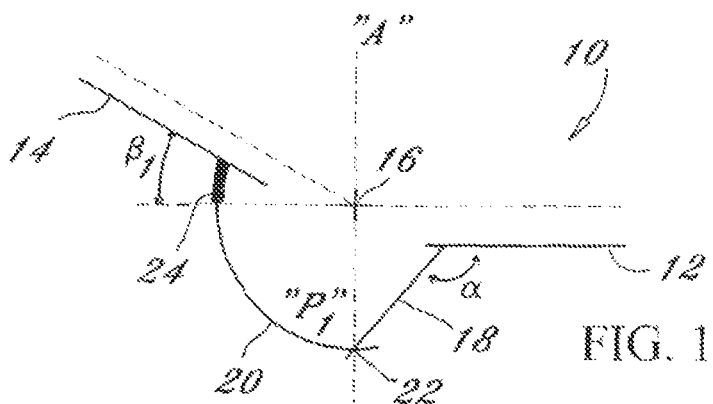
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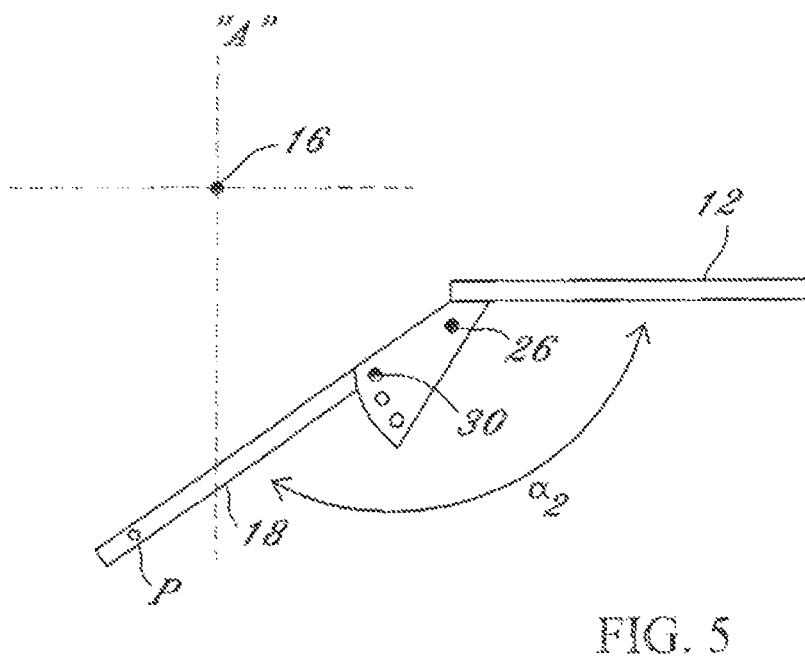
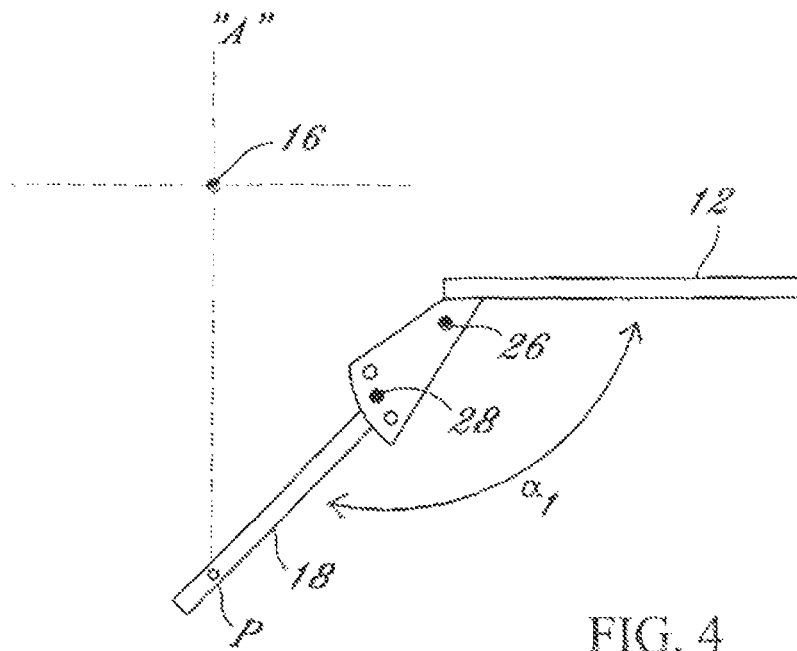
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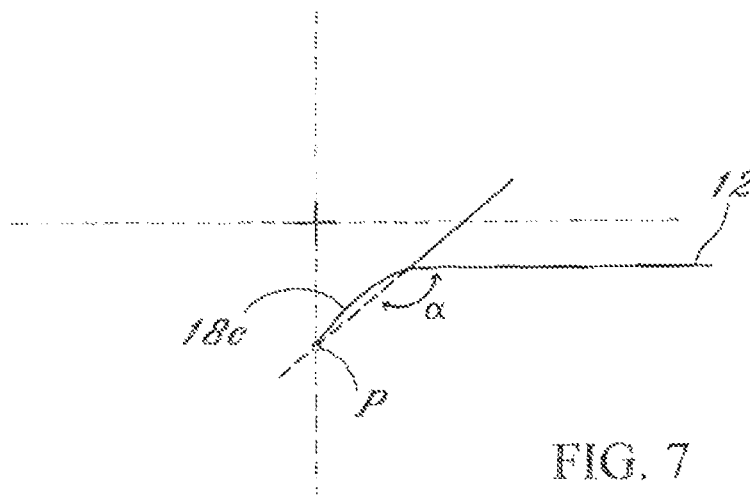
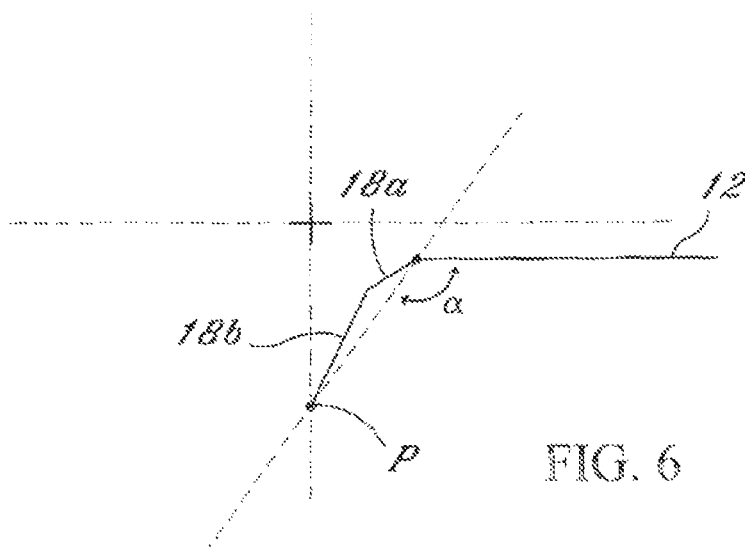
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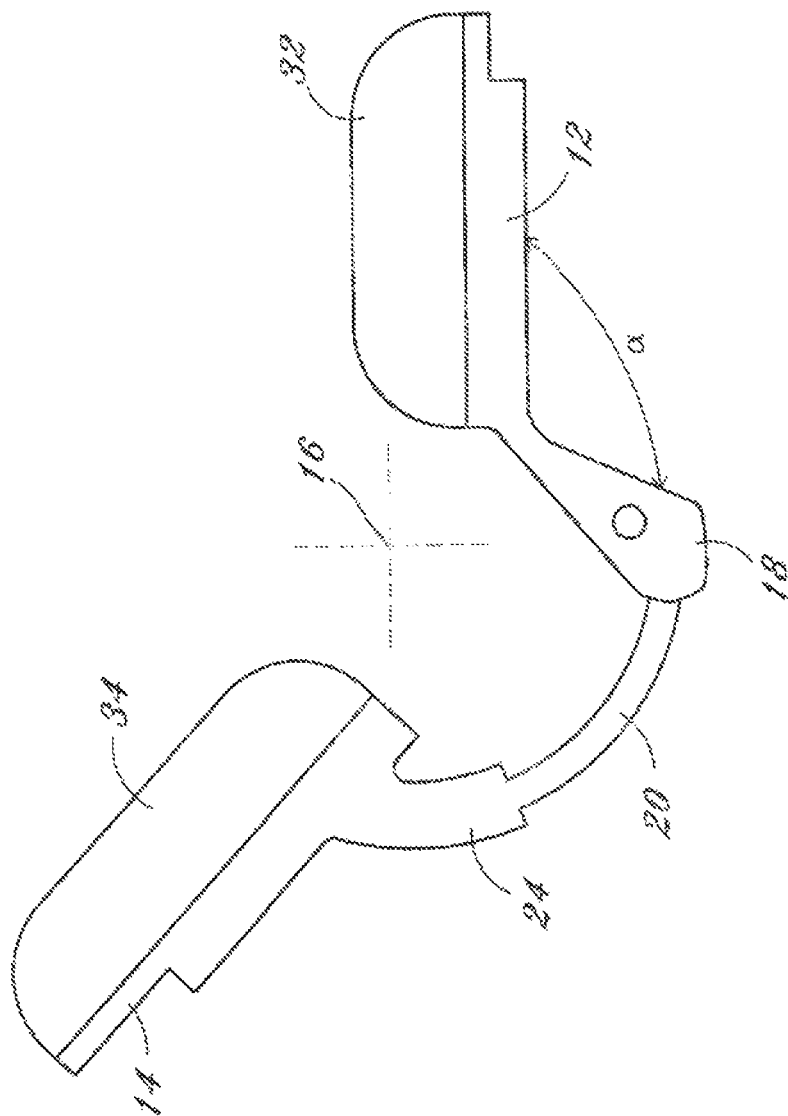


FIG. 8

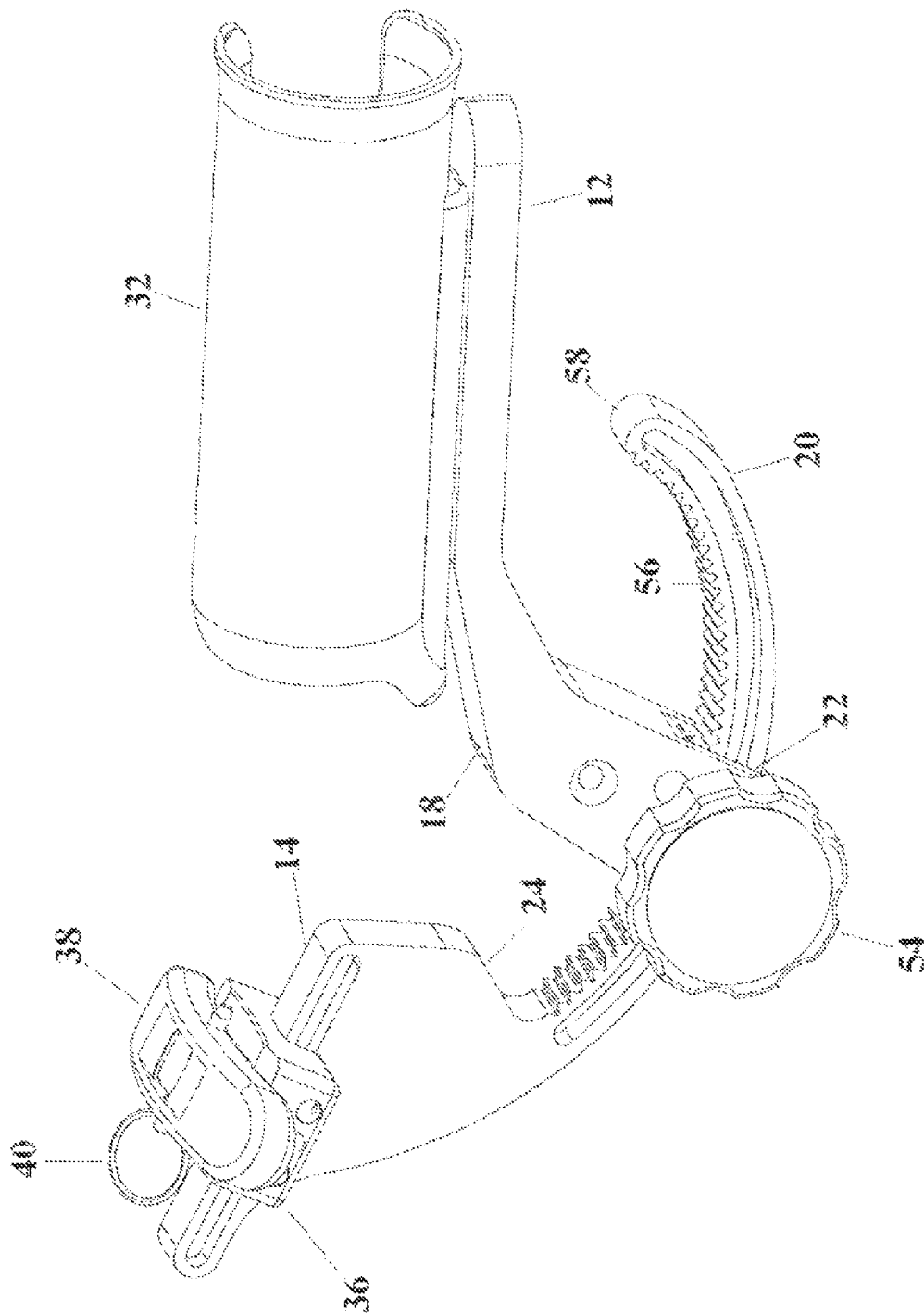


FIG. 9

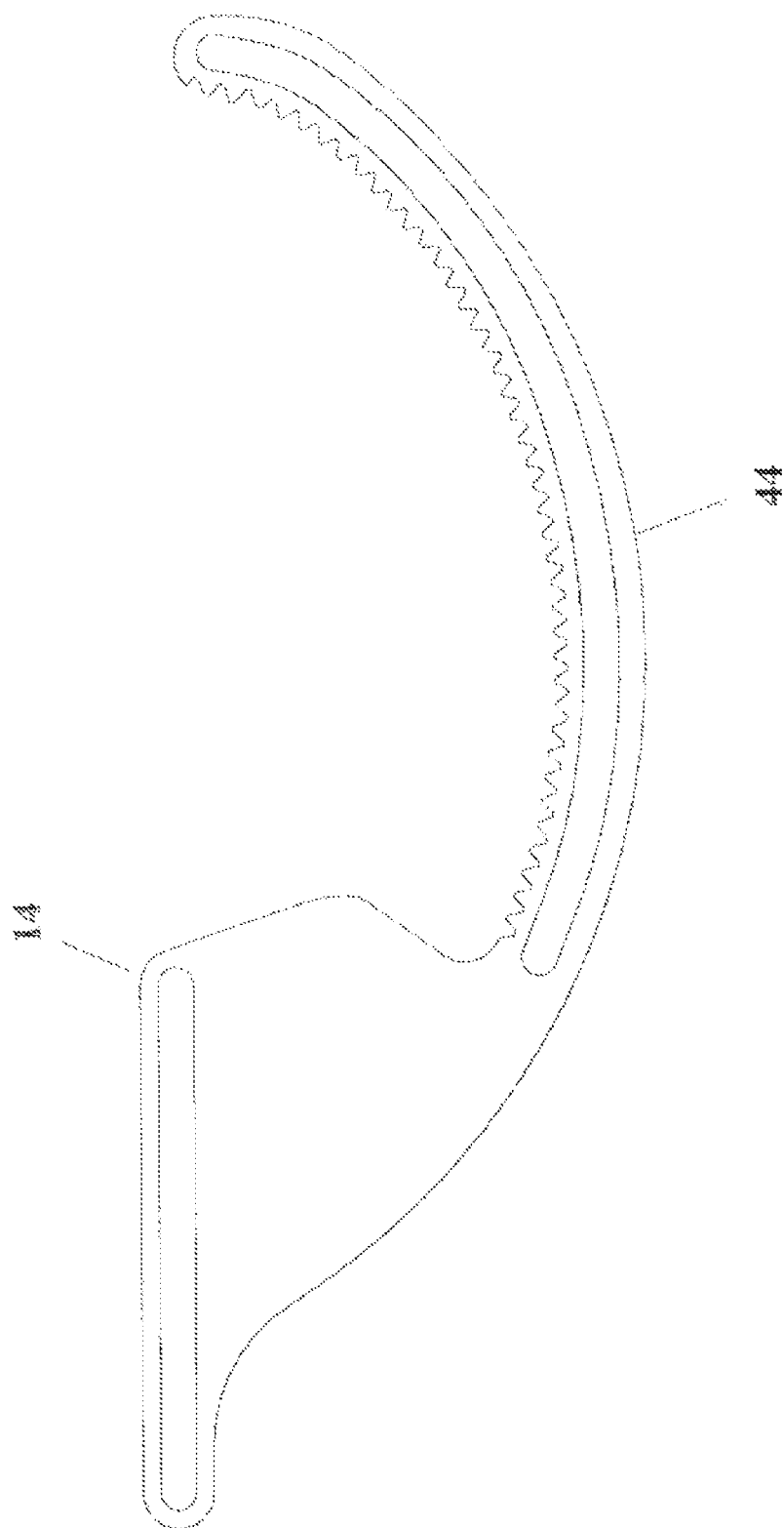


FIG. 10

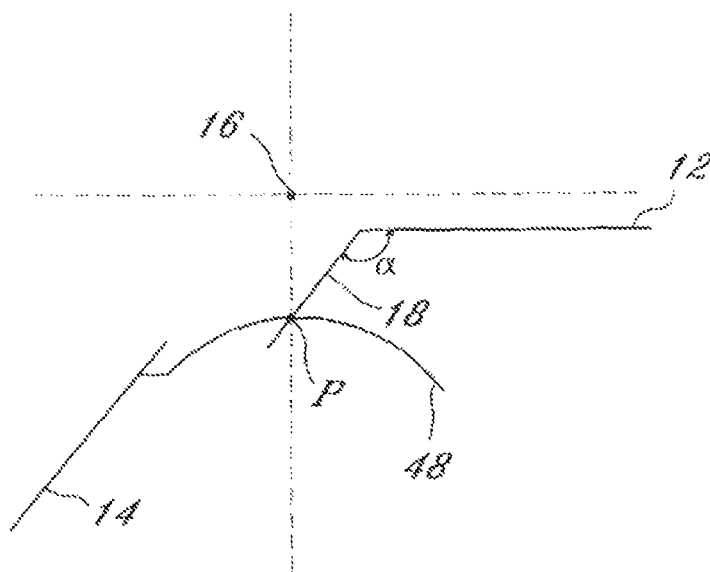


FIG. 11

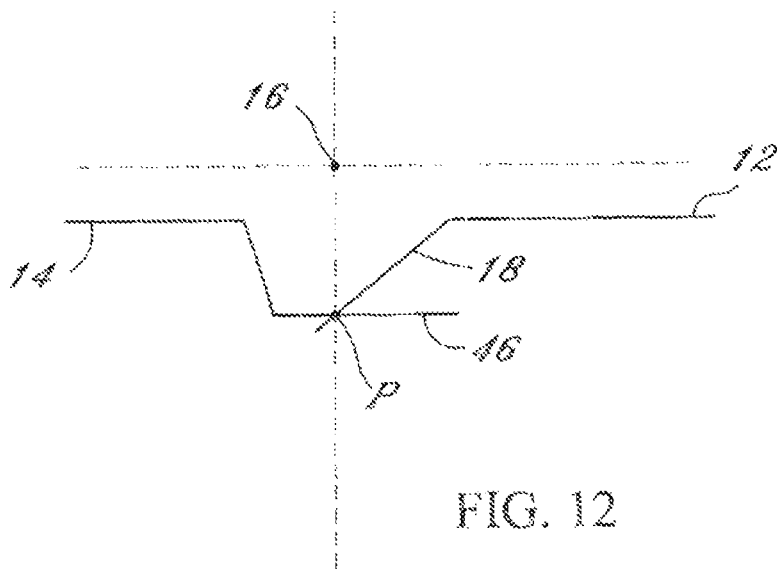


FIG. 12

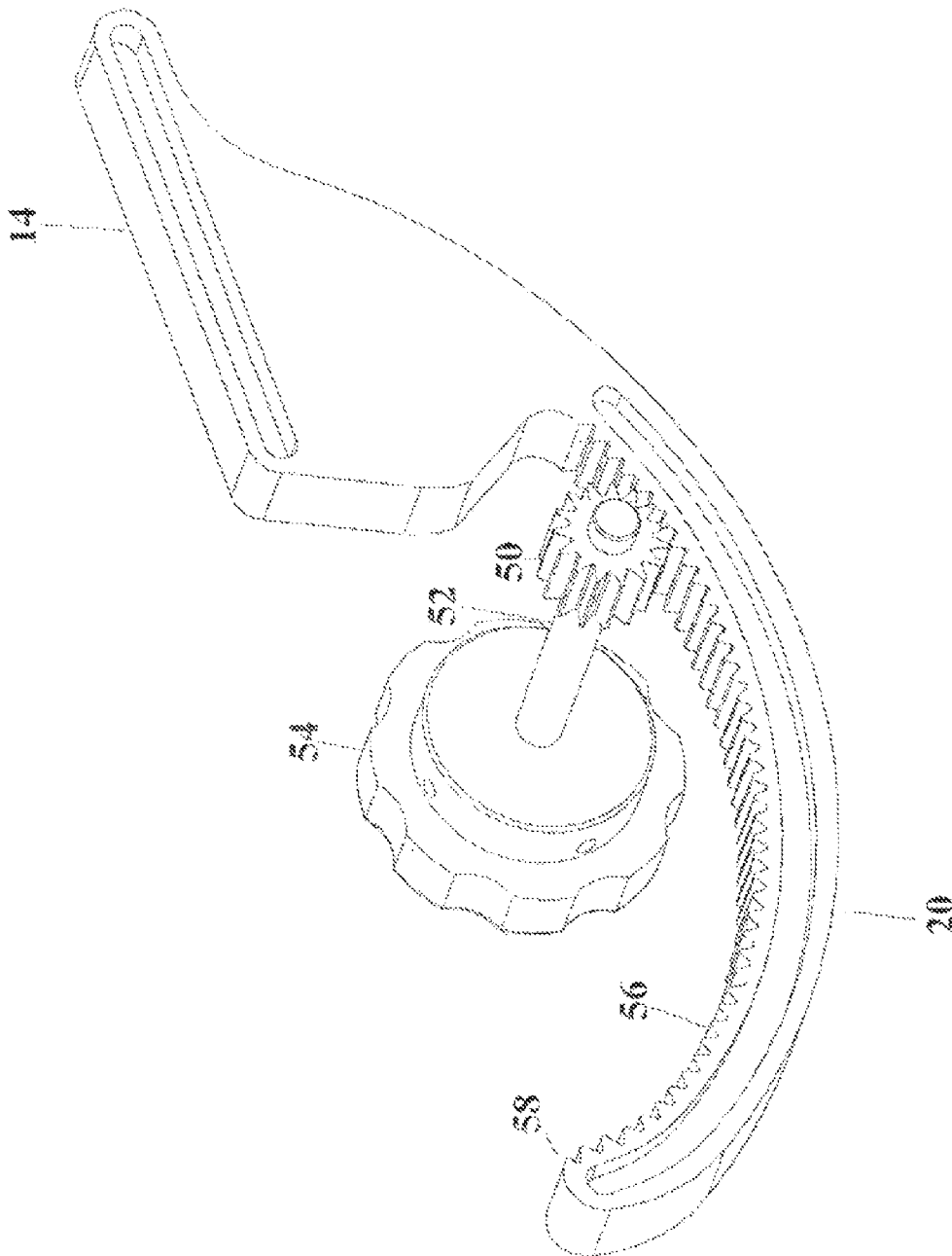


FIG. 13A

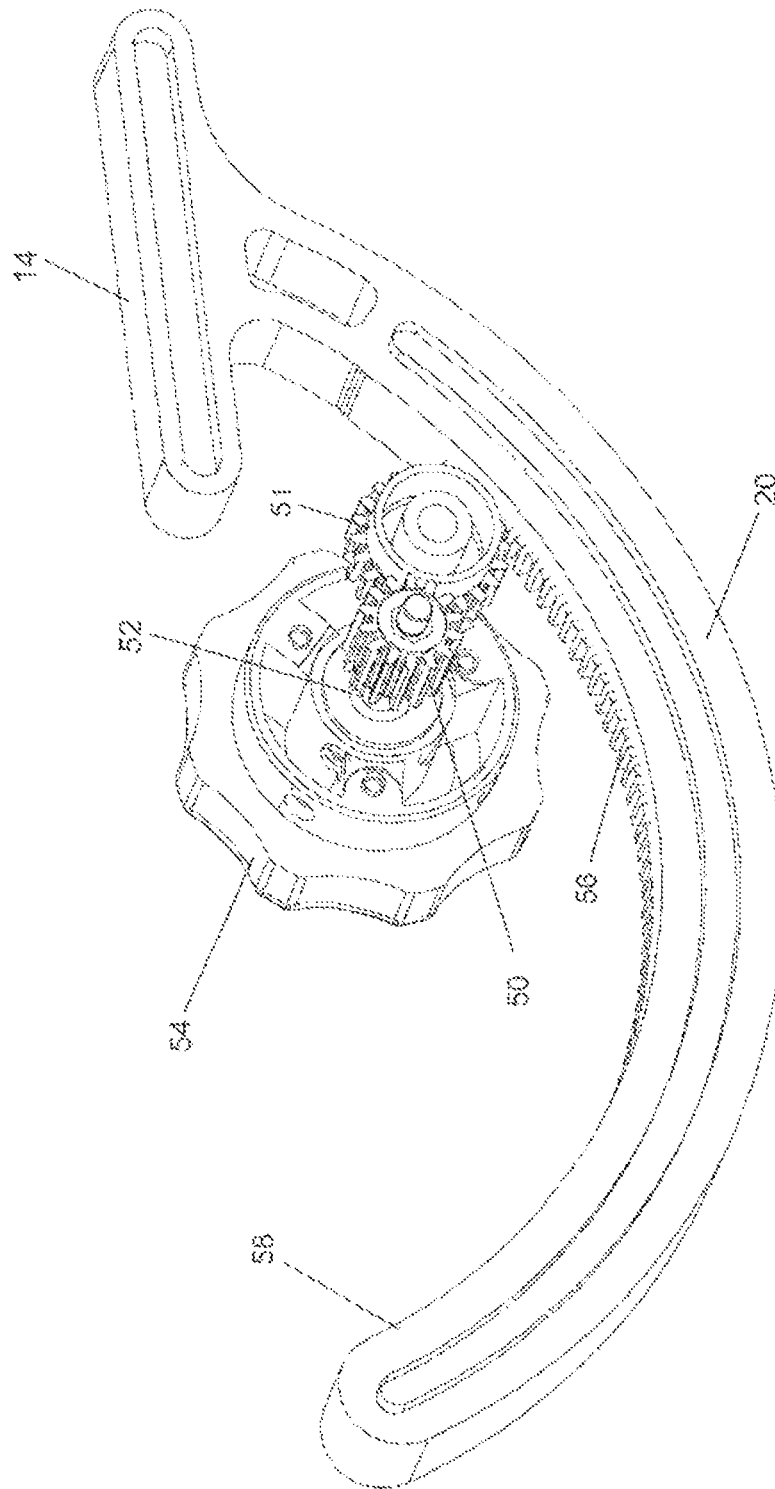


FIG. 13B

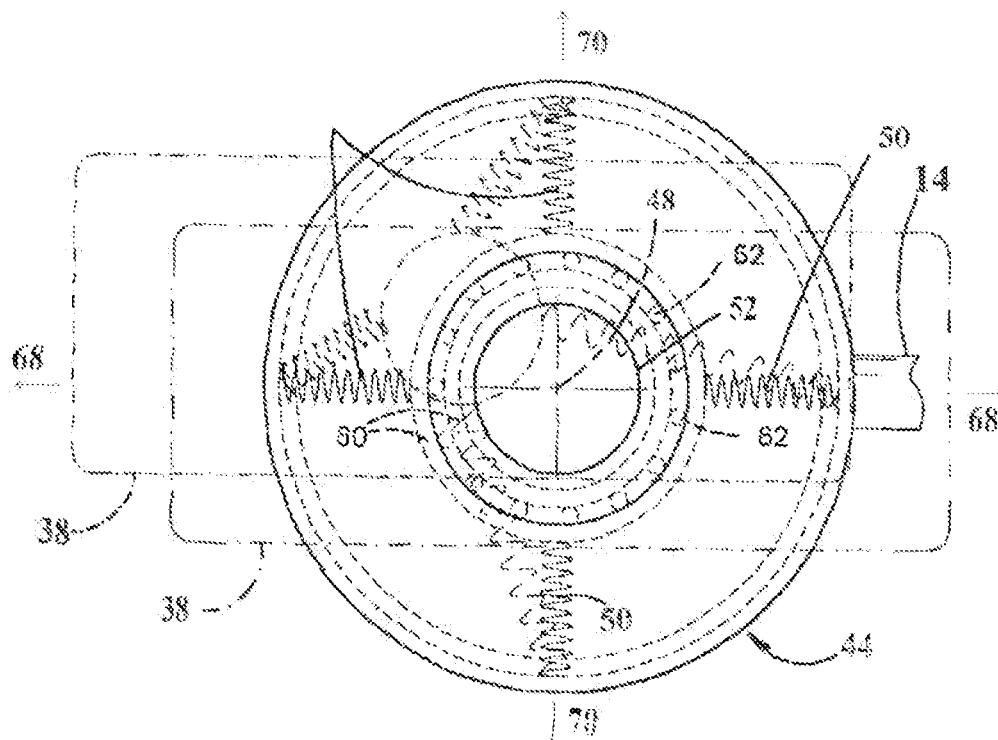


FIG. 14

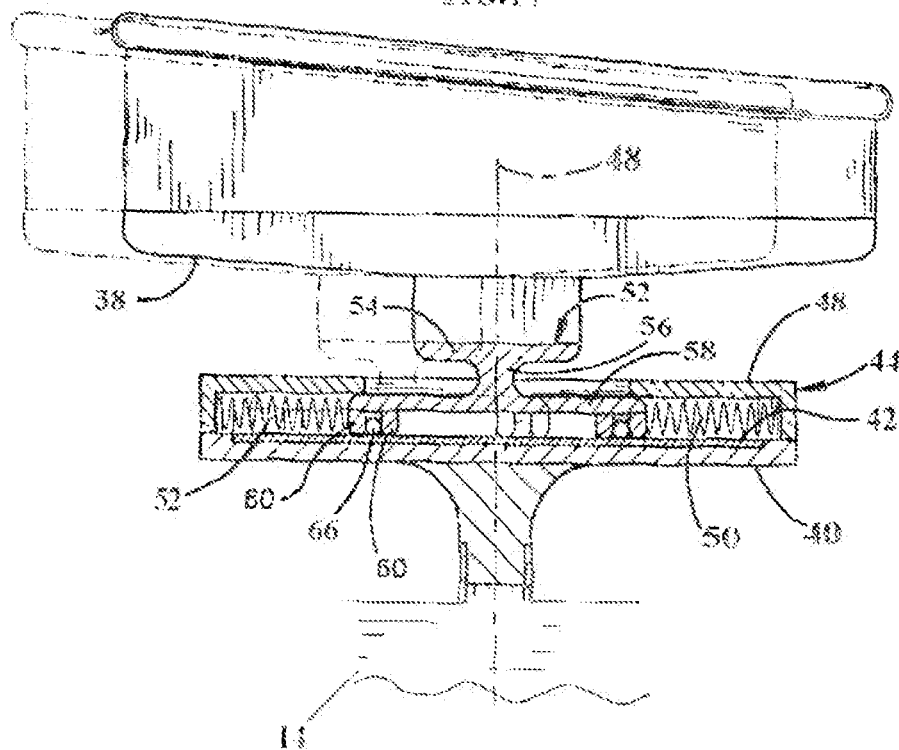


FIG. 15

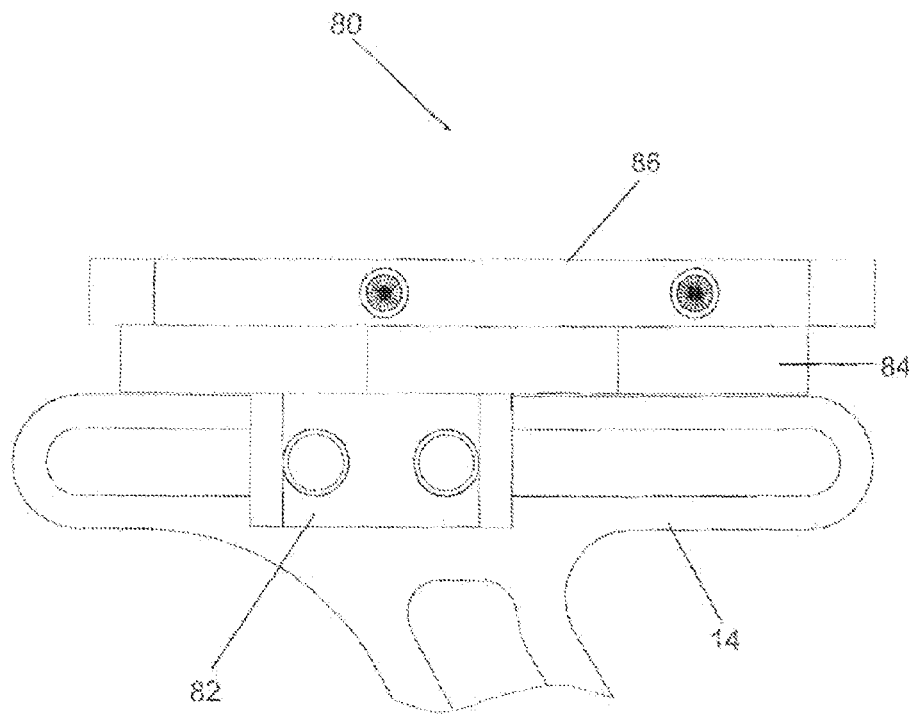


FIG. 16

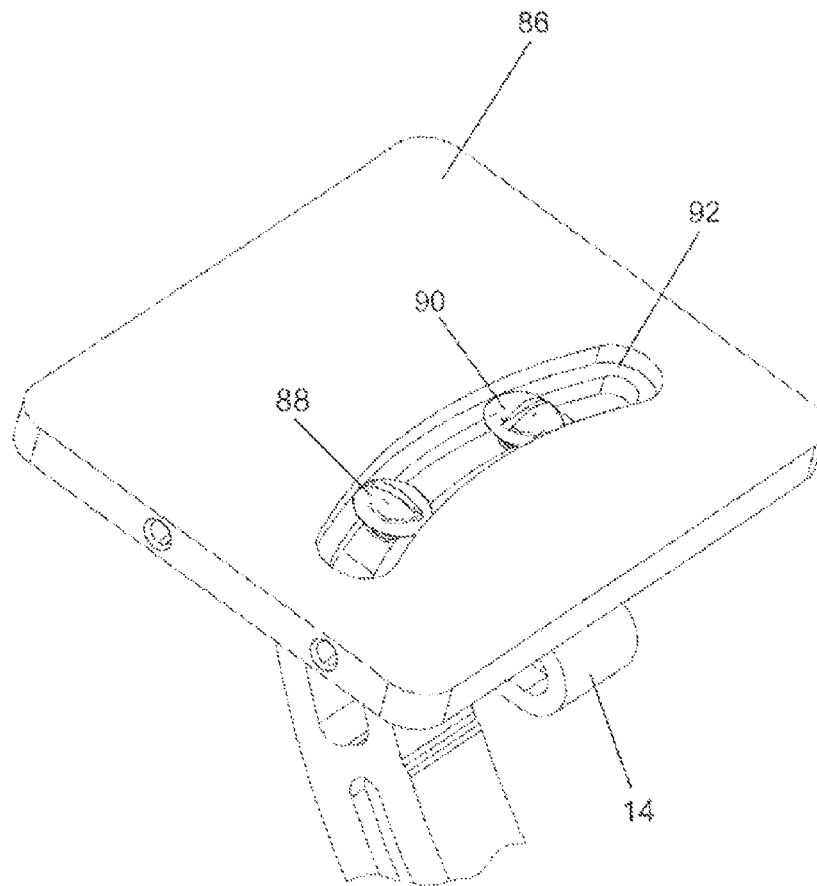


FIG. 17A

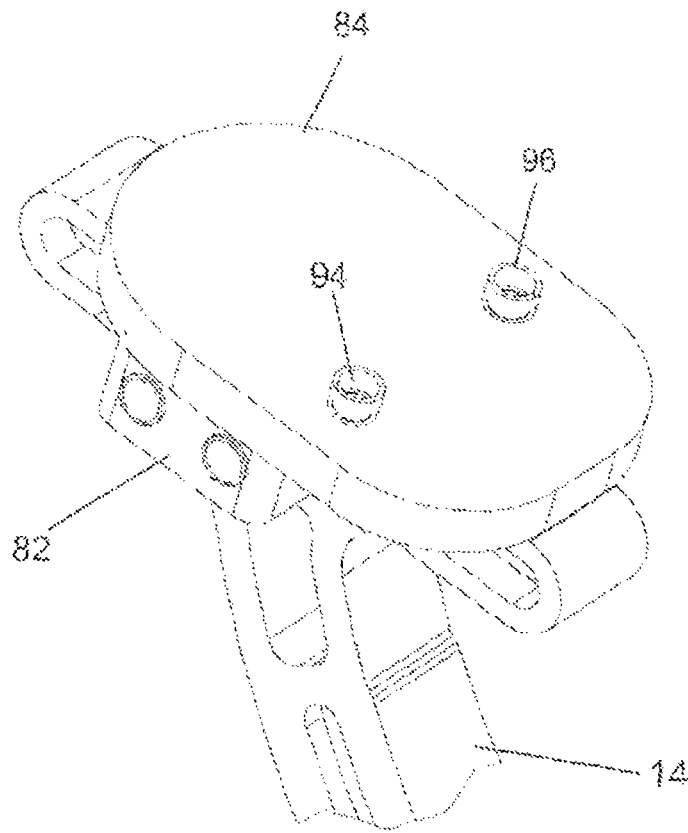


FIG. 17B

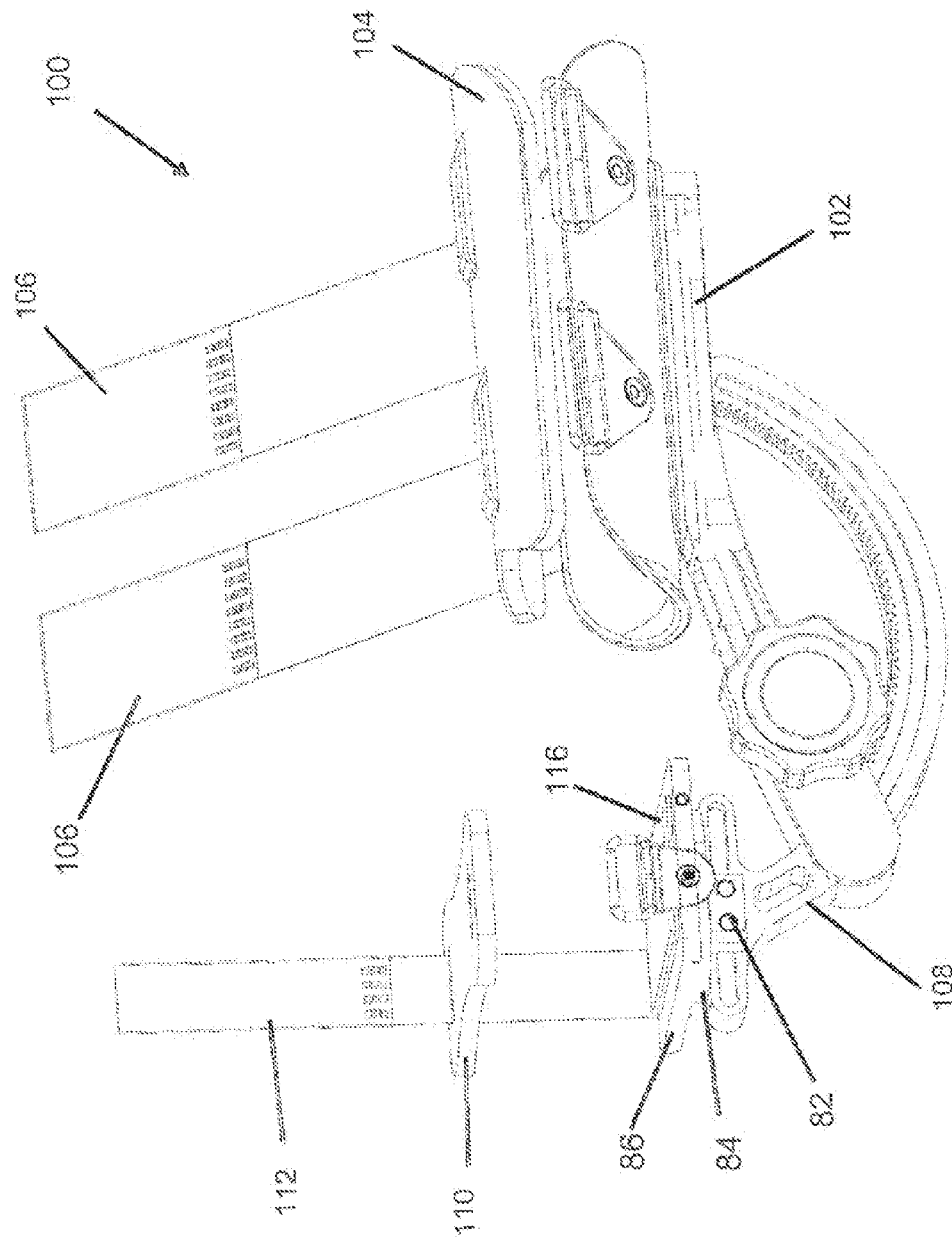


FIG. 18

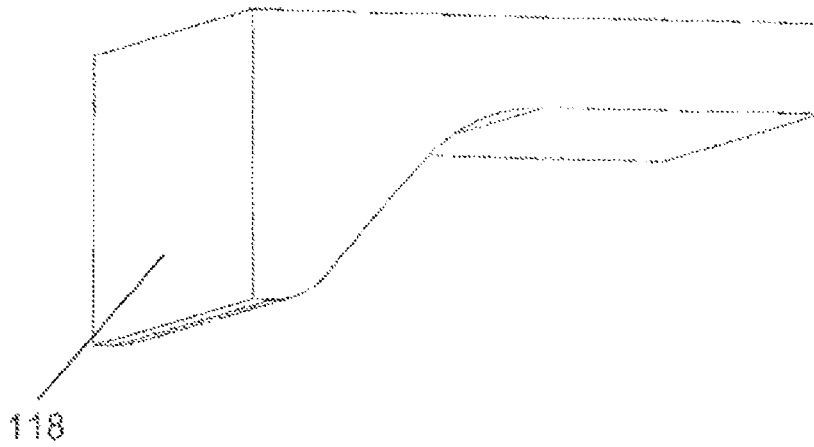


FIG. 20

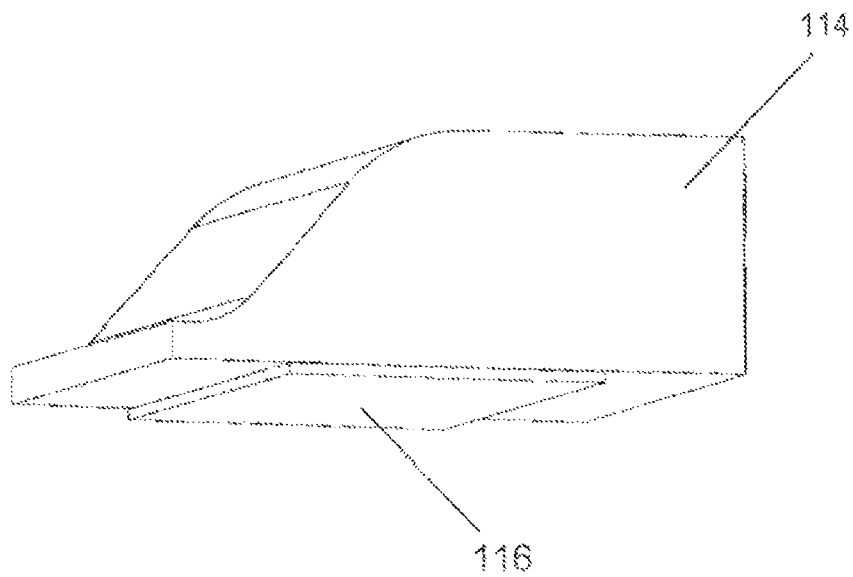


FIG. 19

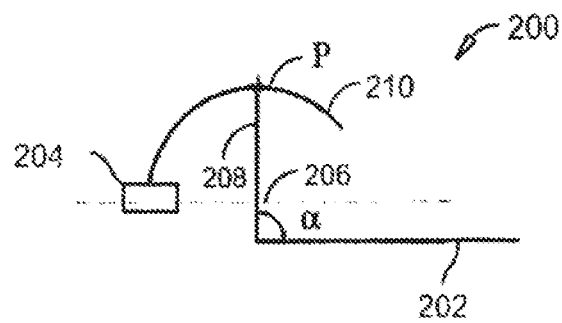


FIG. 21

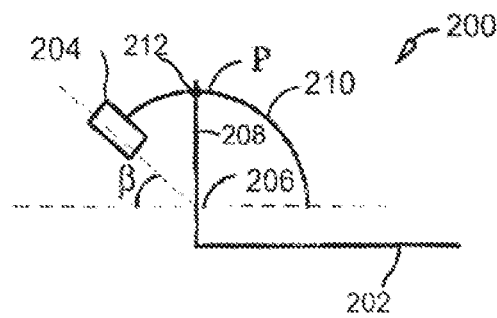


FIG. 22

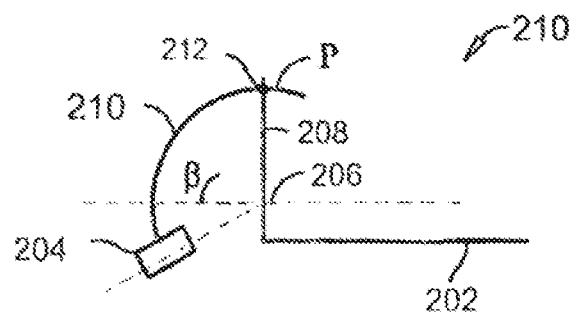


FIG. 23

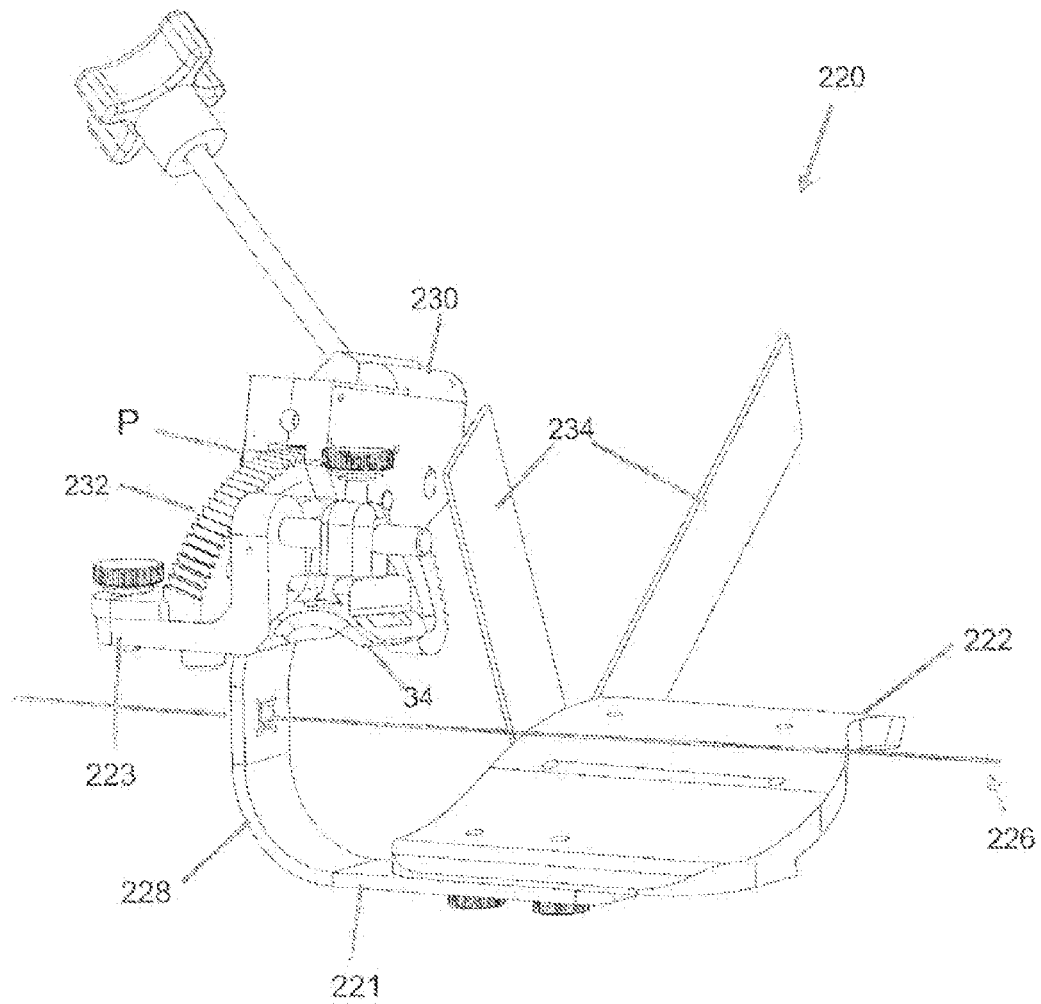


FIG. 24

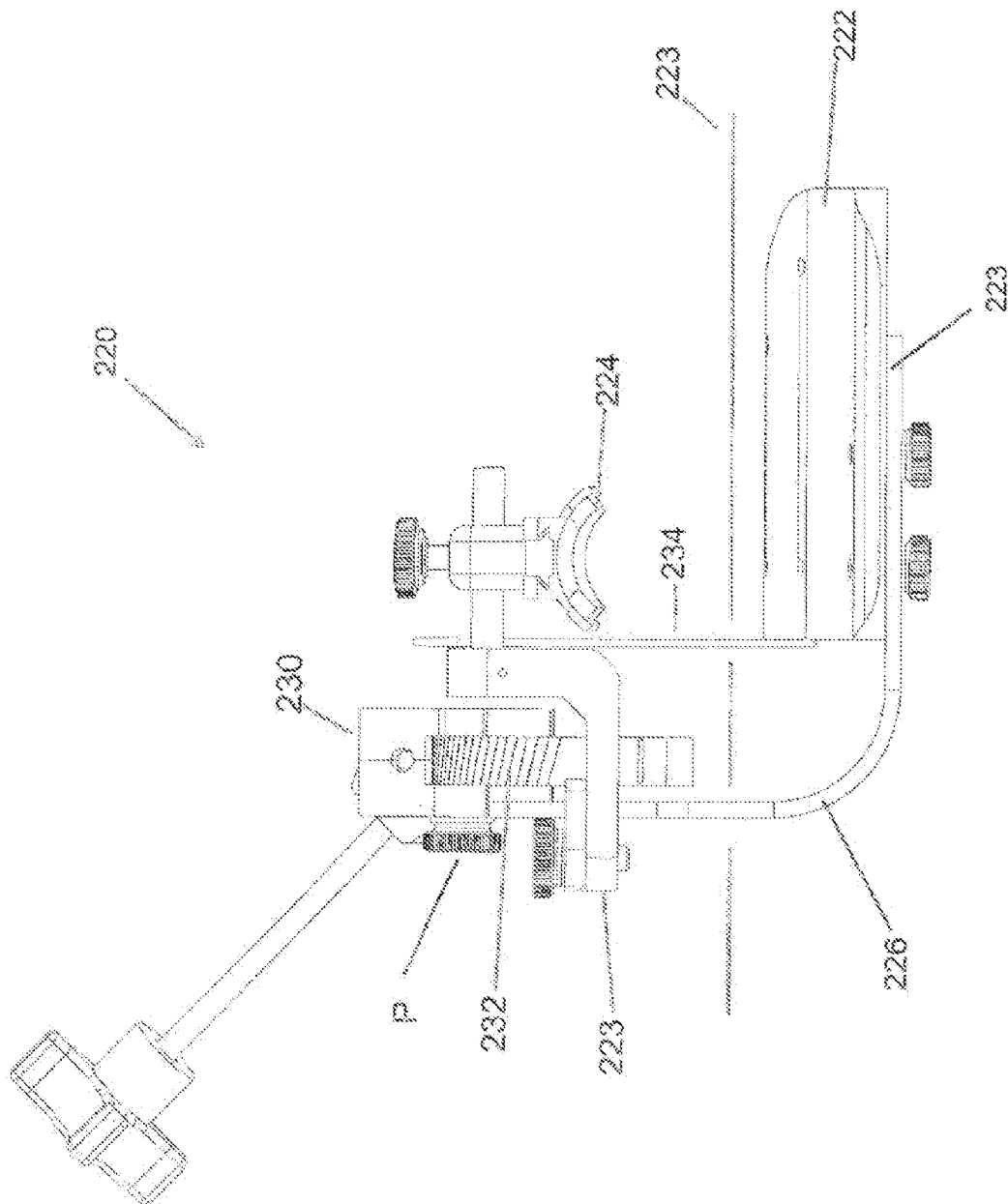


FIG. 25

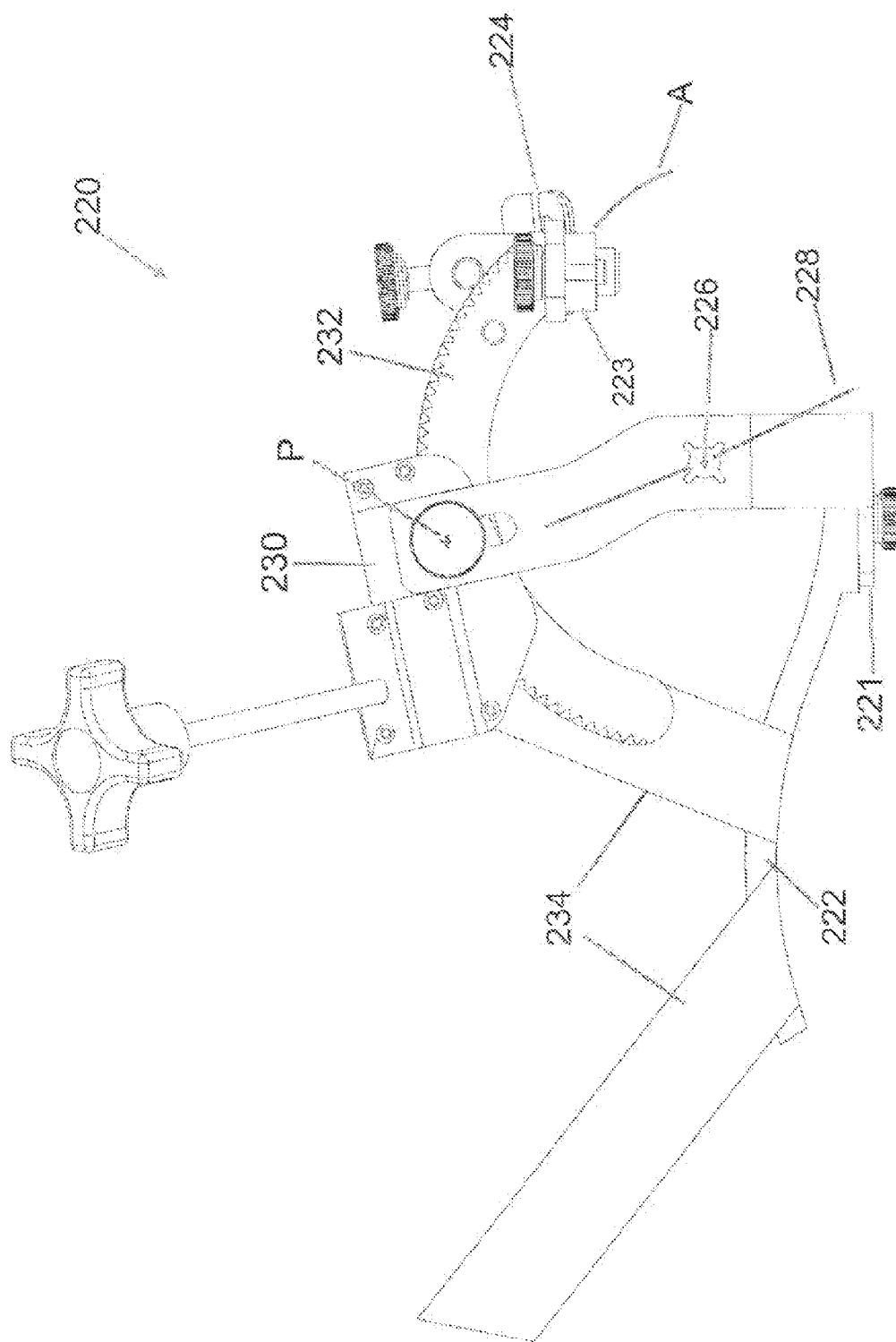


FIG. 26

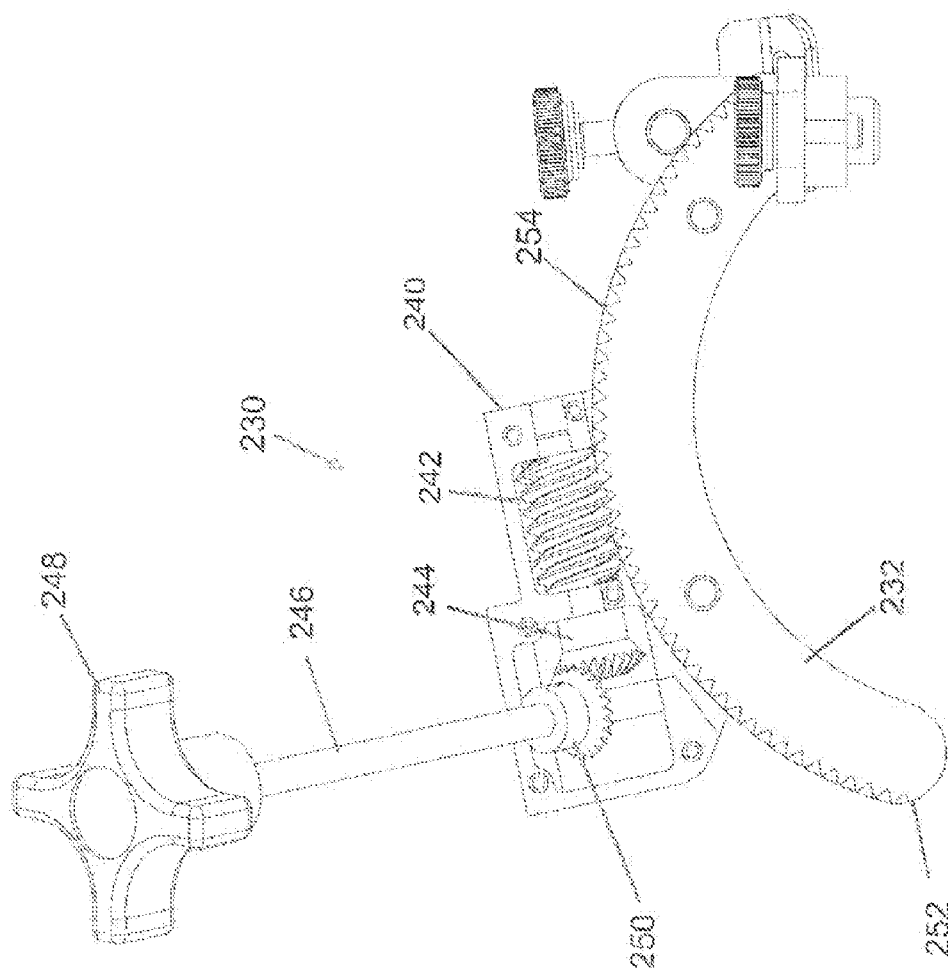


FIG. 27

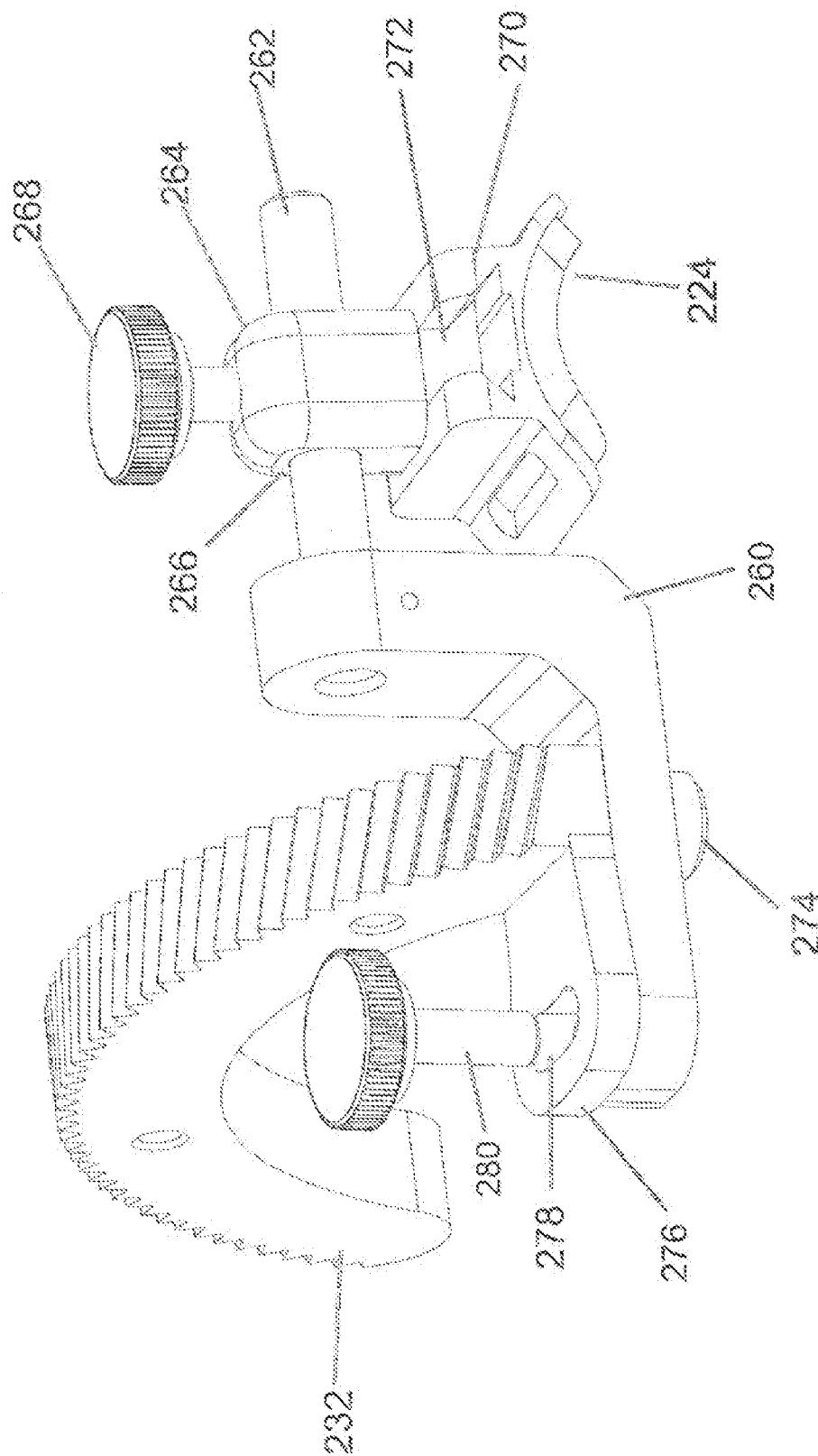


FIG. 28

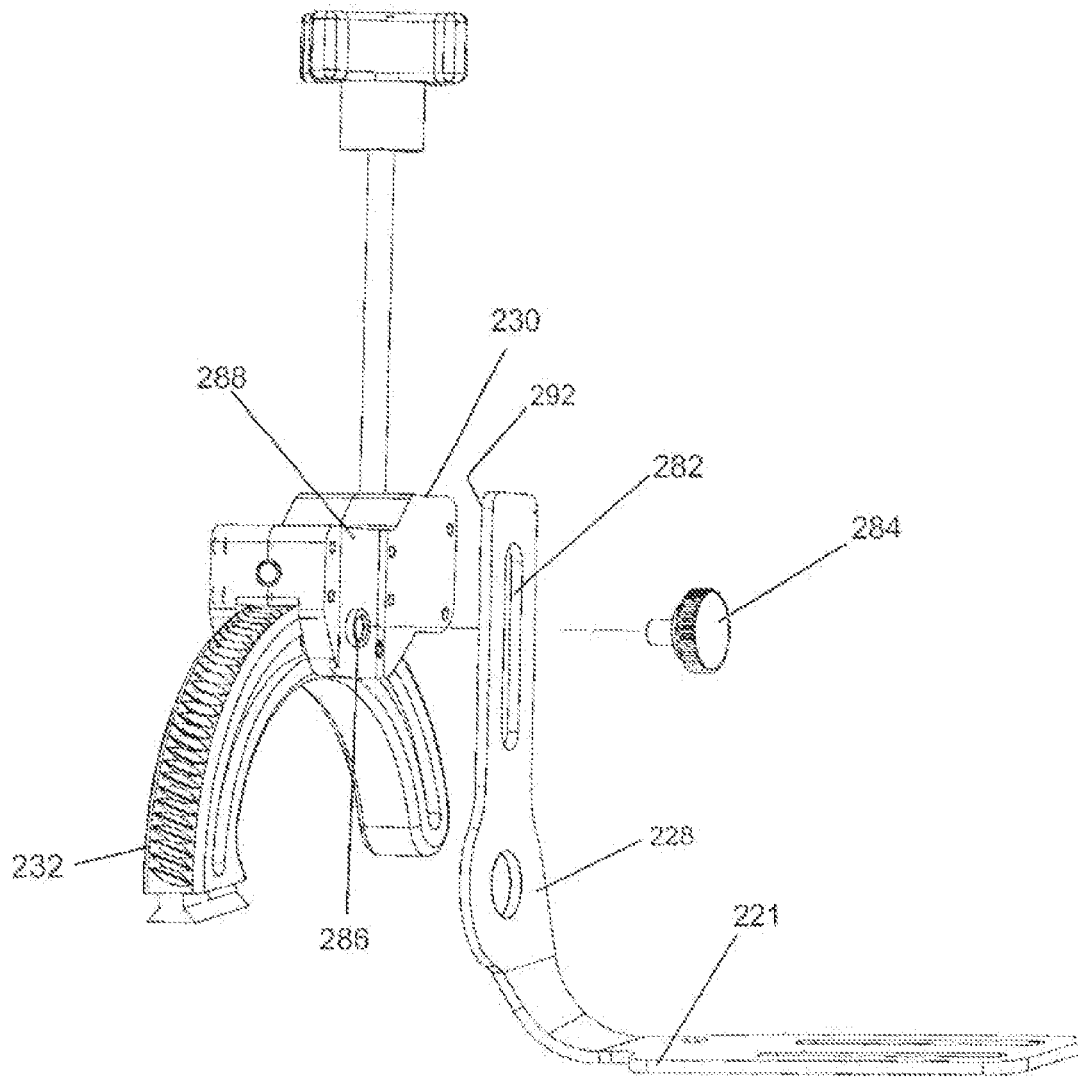


FIG. 29

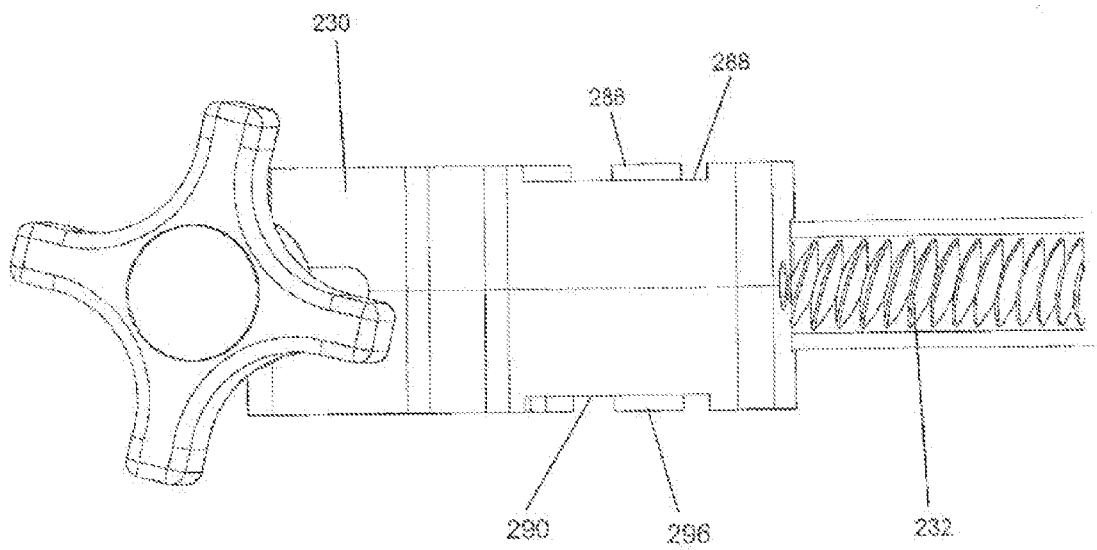


FIG. 30

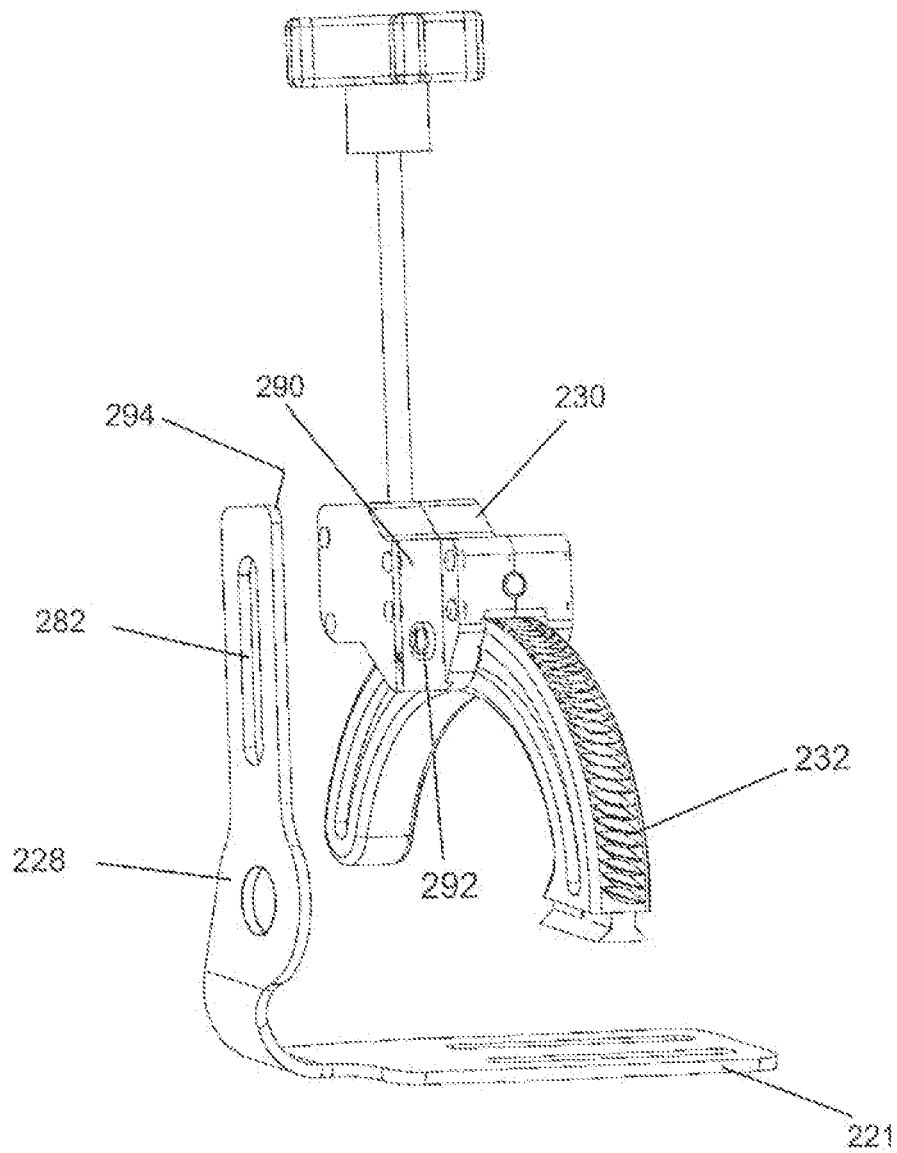


FIG. 31

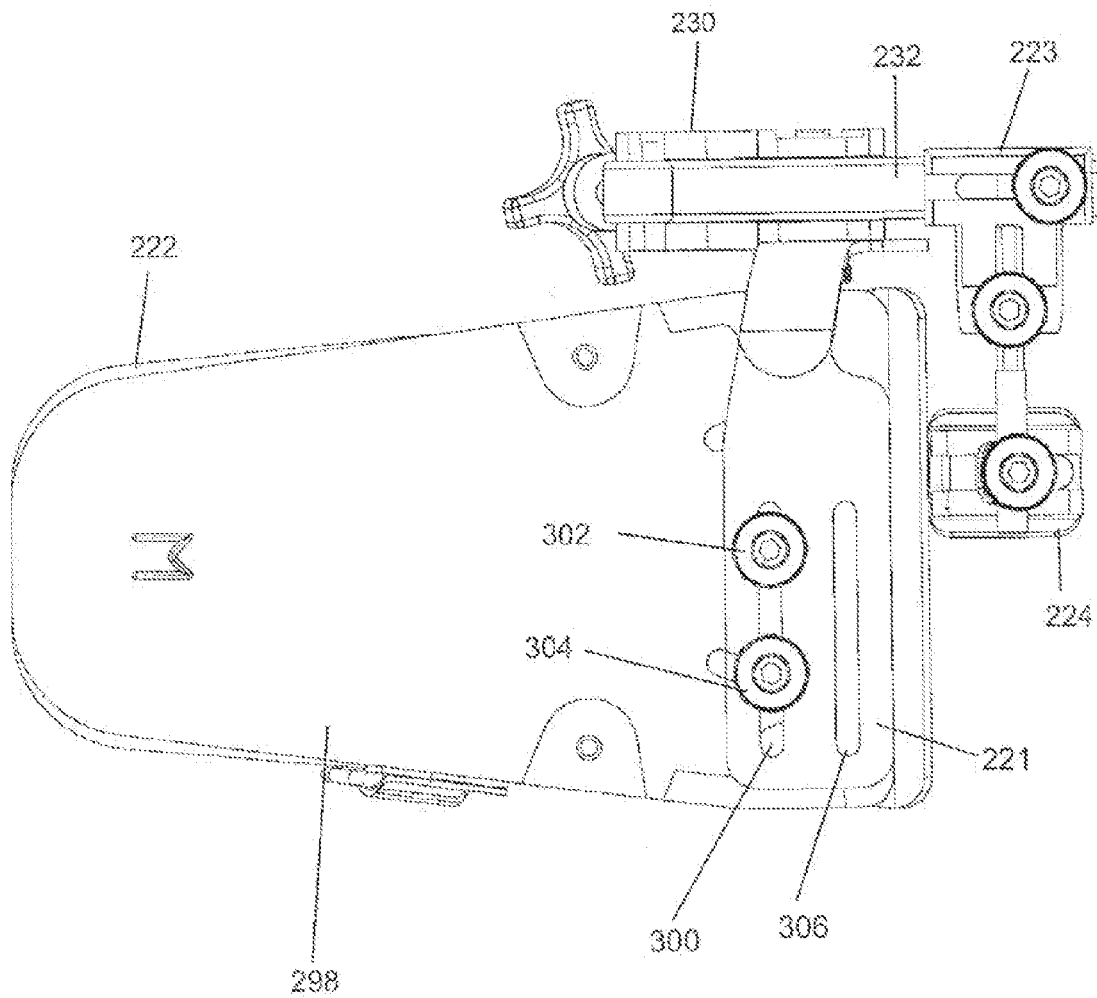


FIG. 32

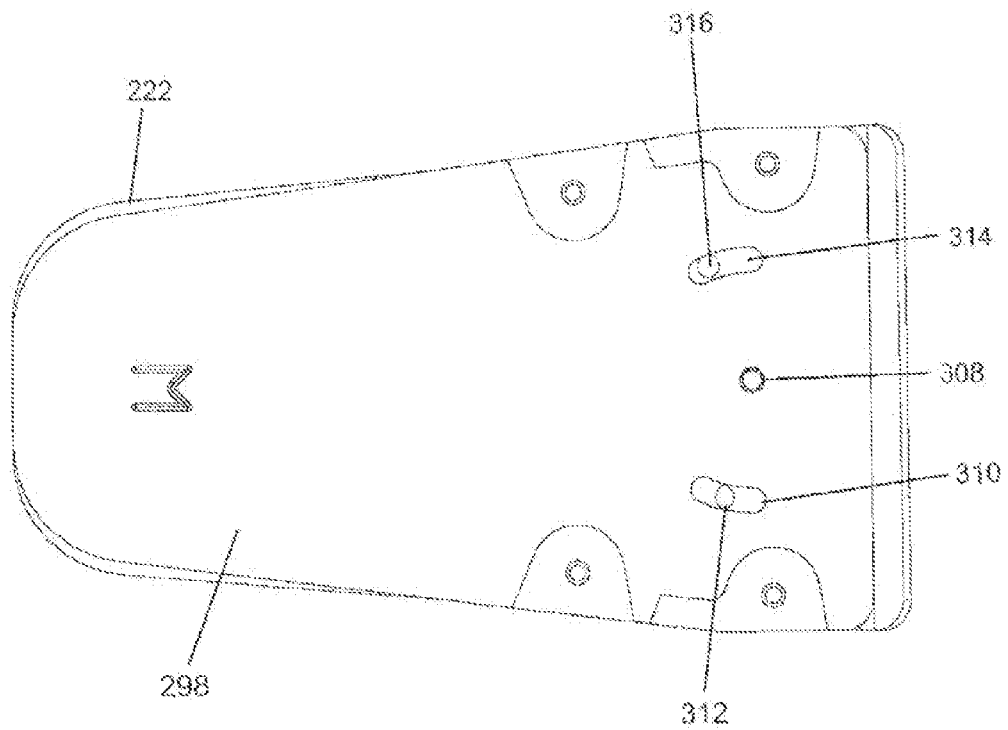


FIG. 33

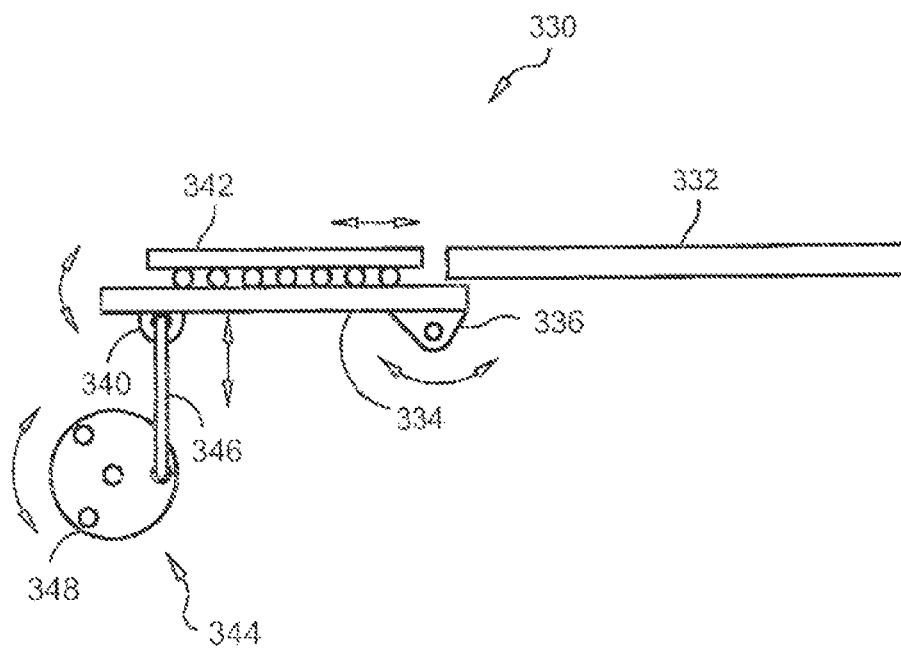


FIG. 34

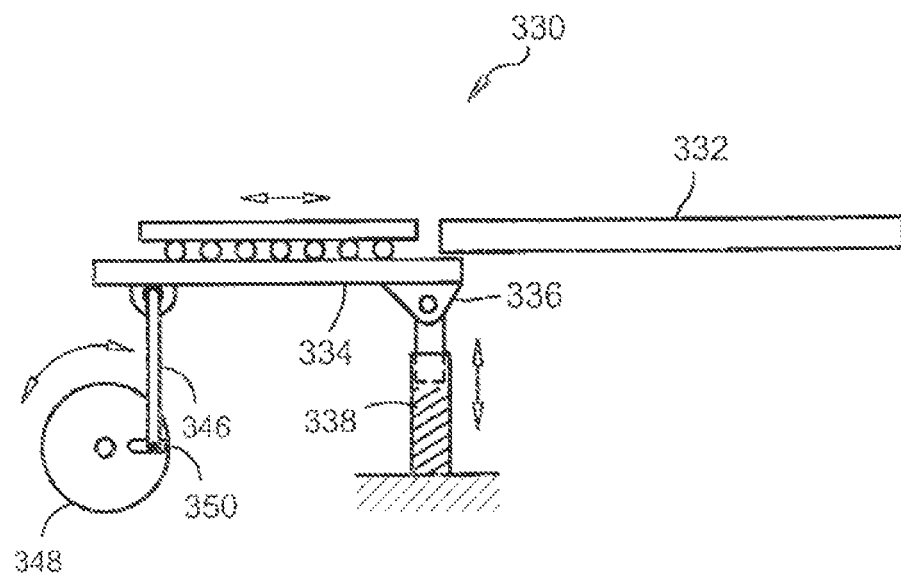


FIG. 35

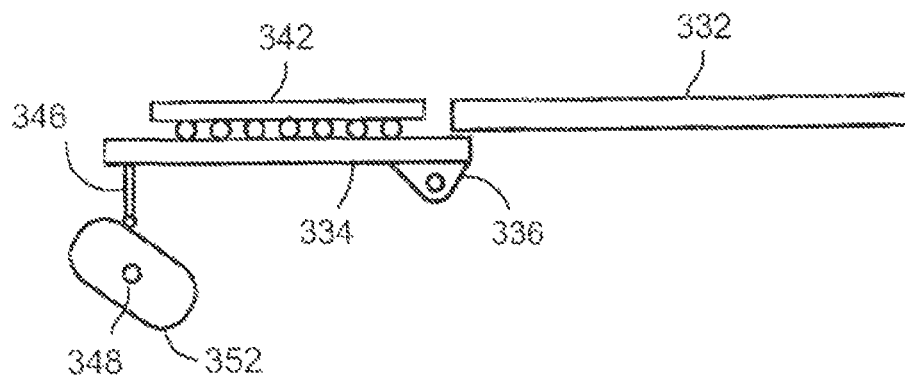


FIG. 36

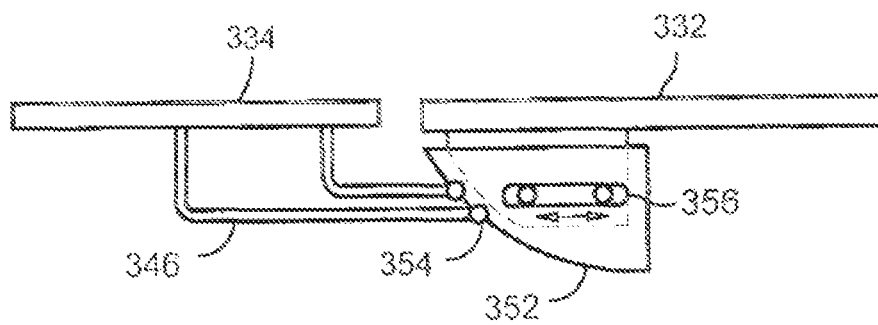


FIG. 37

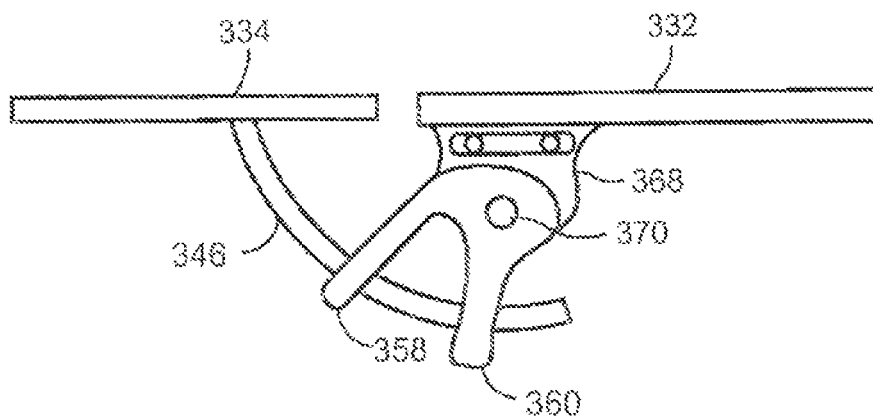


FIG. 38

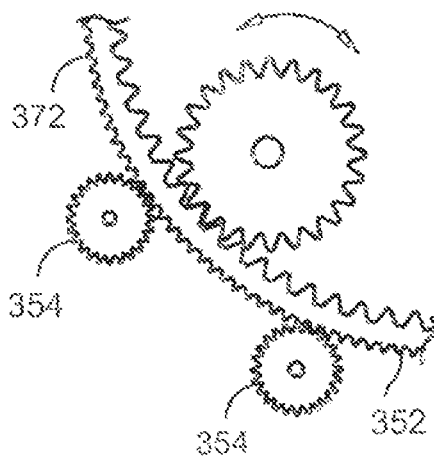


FIG. 39

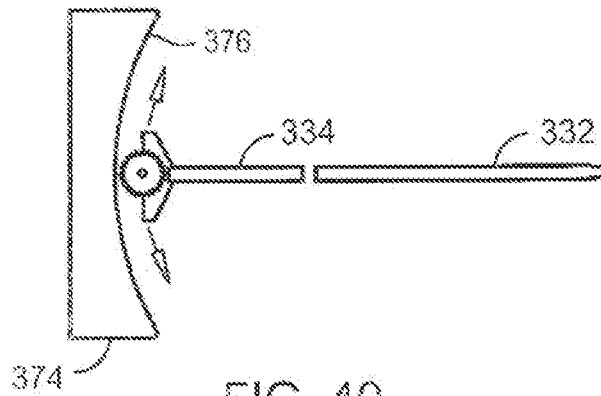


FIG. 40

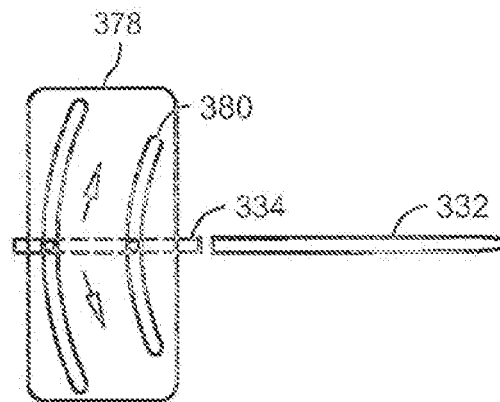


FIG. 41

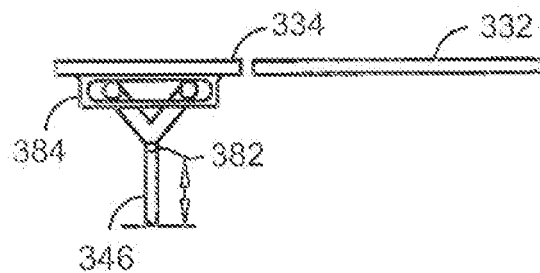


FIG. 42

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**RANGE OF MOTION DEVICE****CROSS-REFERENCE TO RELATED APPLICATIONS**

This patent application is a continuation application of U.S. patent application Ser. No. 14/454,442 filed on Aug. 7, 2014, which is a continuation of U.S. patent application Ser. No. 13/494,103, which is a continuation of U.S. patent application Ser. No. 13/151,962 filed on Jun. 2, 2011, which is a continuation application of U.S. patent application Ser. No. 12/272,436 filed on Nov. 17, 2008, which is a Continuation of U.S. patent application Ser. No. 11/533,839 filed on Sep. 21, 2006, which is a Continuation-In-Part of U.S. patent application Ser. No. 10/795,892 filed on Mar. 8, 2004, which is a Continuation-In-Part of U.S. patent application Ser. No. 11/261,424 filed on Oct. 28, 2005. The contents of each of the above-identified applications are herein incorporated by reference in their entirety.

**FIELD OF THE INVENTION**

The present invention relates to an adjustable orthosis for stretching tissue in the human body. In particular, the present invention relates to an adjustable orthosis which can be used for stretching tissue such as ligaments, tendons or muscles around a joint during flexion or extension of the joint.

**BACKGROUND OF THE INVENTION**

In a joint, the range of motion depends upon the anatomy of that joint and on the particular genetics of each individual. Typically, joints move in two directions, flexion and extension. Flexion is to bend the joint and extension is to straighten the joint; however, in the orthopedic convention some joints only flex. For example, the ankle has dorsiflexion and plantarflexion. Other joints not only flex and extend, they rotate. For example, the elbow joint has supination and pronation, which is rotation of the hand about the longitudinal axis of the forearm placing the palm up or the palm down.

When a joint is injured either by trauma or by surgery, scar tissue can form, often resulting in flexion or extension contractures. Such conditions can limit the range of motion of the joint, limiting flexion (in the case of an extension contracture) or extension (in the case of a flexion contracture) of the injured joint. It is often possible to correct this condition by use of a range-of-motion (ROM) orthosis.

ROM orthoses are devices commonly used during physical rehabilitative therapy to increase the range-of-motion over which the patient can flex or extend the joint. Commercially available ROM orthoses are typically attached on opposite members of the joint and apply a torque to rotate the joint in opposition to the contraction. The force is gradually increased to increase the working range or angle of joint motion. Exemplary orthoses include U.S. Pat. No. 6,599,263, entitled "Shoulder Orthosis;" U.S. Pat. No. 6,113,562, entitled "Shoulder Orthosis;" U.S. Pat. No. 5,848,979, entitled "Orthosis;" U.S. Pat. No. 5,685,830, entitled "Adjustable Orthosis Having One-Piece Connector Section for Flexing;" U.S. Pat. No. 5,611,764, entitled "Method of Increasing Range of Motion;" U.S. Pat. No. 5,503,619, entitled "Orthosis for Bending Wrists;" U.S. Pat. No. 5,456,268, entitled "Adjustable Orthosis;" U.S. Pat. No. 5,453,075, entitled "Orthosis with Distraction through Range of Motion;" U.S. Pat. No. 5,395,303, entitled "Orthosis with Distraction through Range of Motion;" U.S. Pat. No. 5,365,947, entitled "Adjustable Orthosis;" U.S. Pat. No. 5,285,773, entitled

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"Orthosis with Distraction through Range of Motion;" U.S. Pat. No. 5,213,095, entitled "Orthosis with Joint Distraction;" and U.S. Pat. No. 5,167,612, entitled "Adjustable Orthosis;" all to Bonutti and herein are expressly incorporated by reference in their entirety.

**SUMMARY OF THE INVENTION**

The present invention provides an orthosis for stretching tissue around a joint of a patient between first and second relatively pivotable body portions. The joint and the first and second body portions defining on one side of the joint an inner sector which decreases in angle as the joint is flexed and defining on the opposite side of the joint an outer sector which decreases in angle as the joint is extended.

The orthosis includes a first arm member affixable to the first body portion. The first arm member has a first extension member extending at an angle therefrom. A second arm member affixable to the second body portion is also included. The second arm member has a second extension member having an arcuate shape extending therefrom. The second and first extension members are operatively connected, such that the second extension member travels through the first extension member along an arcuate path when the second arm member is moved from a first position to a second position relative to the first arm member.

The orthosis further includes a drive assembly for selectively moving the second extension member relative to the first extension member. The drive assembly is mounted onto the first extension member, engaging the second extension member. The drive assembly can be manually or automatically actuated to selectively move the second extension member relative to the first extension member.

**BRIEF DESCRIPTION OF THE DRAWINGS**

A more complete understanding of the present invention, and the attendant advantages and features thereof, will be more readily understood by reference to the following detailed description when considered in conjunction with the accompanying drawings wherein:

FIG. 1 is a schematic diagram of the orthosis of the present invention in a flexed position;

FIG. 2 is a schematic diagram of the orthosis of the present invention in an extended position;

FIG. 3 is a second schematic diagram of the orthosis of the present invention in a flexed position;

FIG. 4 shows an adjustable first extension member of the orthosis of the present invention;

FIG. 5 shows the adjustable first extension member of FIG. 4 in a second position;

FIG. 6 shows a segmented first extension member of the present invention;

FIG. 7 shows an arcuate first extension member of the present invention;

FIG. 8 shows an orthosis of the present invention;

FIG. 9 shows an orthosis of the present invention for flexing and extending a wrist joint in a patient;

FIG. 10 shows a non-circular arcuate shaped second extension member of the present invention;

FIG. 11 shows an alternative arcuate shaped second extension member of the present invention;

FIG. 12 shows a linear shaped second extension member of the present invention;

FIGS. 13A and B show exemplary drive assemblies of the present invention;

FIG. 14 is a top plan view of portions of an articulating hand pad support of the present invention;

FIG. 15 is a schematic sectional view of the articulating hand pad support of FIG. 14;

FIG. 16 depicts a side view of another articulating hand pad support of the present invention;

FIG. 17A depicts a top view of the articulating hand pad support of FIG. 16;

FIG. 17B depicts a top view of the articulating hand pad support of FIG. 16 with the pivoting plate removed;

FIG. 18 shows an orthosis of the present invention;

FIG. 19 shows a hand pad for the orthosis of FIG. 18;

FIG. 20 shows another hand pad for the orthosis of FIG. 18;

FIG. 21 is a schematic diagram of an orthosis of the present invention;

FIG. 22 is a schematic diagram of the orthosis of FIG. 21 in an extended position;

FIG. 23 is a schematic diagram of the orthosis of FIG. 21 in a flexed position;

FIG. 24 is an isometric view of an orthosis of the present invention;

FIG. 25 is a front view of the orthosis of FIG. 24;

FIG. 26 is a side view of the orthosis of FIG. 24;

FIG. 27 is a sectional view of a drive assembly of the orthosis of FIG. 24;

FIG. 28 is a section view of an adjustable second cuff for the orthosis of FIG. 24;

FIG. 29 is an expanded view of the drive assembly connection to the first member of the orthosis of FIG. 24;

FIG. 30 is a top view of the drive assembly of the orthosis of FIG. 24;

FIG. 31 is an expanded view of another drive assembly connection to the first member of the orthosis of FIG. 24;

FIG. 32 depicts a bottom view of the orthosis of FIG. 24.

FIG. 33 depicts a bottom view of a first cuff of the orthosis of FIG. 24;

FIG. 34 is a schematic diagram of an embodiment of an orthosis of the present invention;

FIG. 35 illustrates another embodiment of the invention utilizing a cushion or spring;

FIG. 36 is an embodiment of the invention illustrating the use of a cam surface;

FIG. 37 is an embodiment of the invention utilizing a slideable arcuate surface;

FIG. 38 illustrates features of an orthosis of the invention where the relative positions of component parts of the orthosis are adjustable;

FIG. 39 is an illustration of the use of gears with an arcuate or cam surface of an orthosis of the invention;

FIG. 40 is a schematic diagram of an embodiment of the invention using an arcuate path and gear or cam follower;

FIG. 41 illustrates the use of a multi-slotted component to control movement of the orthosis; and

FIG. 42 illustrates an embodiment of the invention where linear movement of a component is translated into rotational and translational movement of another component of the orthosis.

### DETAILED DESCRIPTION OF THE INVENTION

The present invention relates to an orthosis for moving a joint between first and second relatively pivotable body portions. The joint and the first and second body portions define on one side (the flexor side) of the joint an inner sector which decreases in angle as the joint is flexed (bent) and on the opposite side (the extensor side) of the joint an outer sector which decreases in angle as the joint is extended (straight-

ened). The orthosis of the present invention is affixable to either the flexor or extensor side of the joint for treatment of flexion or extension contractures.

Referring now to the drawing figures in which like reference designators refer to like elements, there is shown in FIG. 1, a schematic of the orthosis 10 of the present invention. The orthosis 10 includes a first arm member 12 attachable to the first body portion and a second arm member 14 attachable to the second body portion, wherein a joint axis of rotation 16 is interposed between and offset from the first and second arm members 12 and 14. The first and second arm members 12 and 14 are operatively connected to each other offset from the joint axis 16.

The first arm member 12 of the orthosis 10 includes a first extension member 18, which extends at angle  $\alpha$  from the first arm member 12. The second arm member 14 of the orthosis 10 includes a second extension member 20 extending therefrom and having an arcuate shape. The first and second extension members 18 and 20 are operatively connected at point "P," such that in operation the second extension member 20 travels along an arcuate path about and substantially through point "P." The arcuate shape of the second extension member 20 results in the second body portion rotating about the joint axis 16, when the second arm member 14 is moved from a first position to a second position relative to the first arm member 12. The angle  $\alpha$  between the first extension member 18 and the first arm member 12 and the radius of curvature of the second extension member 20 are a function of the joint to be treated and the degree of flexion or extension contractures.

The orthosis further includes a drive assembly 22 at point "P." The drive assembly connects the first and second extension members 18 and 20 for applying force to the first and second arm members 12 and 14 to pivot the first and second body portions relative to each other about the joint.

The orthosis 10 of the present invention is shown having an angle  $\alpha$  such that the operative connection, at point "P," of the first and second extensions 18 and 20 is located in a plane "A" passing through the joint axis 16, wherein plane "A" is substantially orthogonal to a longitudinal axis of the first arm member 12. This position of point "P" provides an angle  $\beta_1$  between the second arm member 14 and the joint axis 16, wherein  $\beta_1$  is the maximum angle of flexion. As shown in FIG. 2, the second extension member includes a stop 24. The stop 24 acts to limit the angle of maximum extension  $\gamma$  between the second arm member 14 and the joint axis 16. An increase in the length of the stop 24 will decrease the angle of maximum extension  $\gamma$ . A decrease in the length of the stop 24 will increase the angle of maximum extension  $\gamma$ .

Referring to FIG. 3, the maximum flexion angle can be increased by increasing the angle  $\alpha$ . An increase in the angle  $\alpha$  will move the point "P" to a location "in front of" the plane "A." This position of point "P" provides an angle  $\beta_2$  between the second arm member 14 and the joint axis 16 in maximum flexion, wherein  $\beta_2$  is greater than  $\beta_1$ . The greater the angle  $\alpha$ , the greater the angle of maximum flexion.

Alternatively, (not shown) a decrease in the angle  $\alpha$  will move the point "P" to a location "behind" the plane "A." This position of point "P" provides an angle  $\beta_3$  between the second arm member 14 and the joint axis 16 in maximum flexion, wherein  $\beta_3$  is less than  $\beta_1$ . The smaller the angle  $\alpha$ , the smaller the angle  $\beta$  of maximum flexion.

Referring to FIG. 4, the first extension member 18 is selectively, pivotally connected at location 26 to the first arm member 12. The pivotal connection 26 of the first extension member 18 permits the angle  $\alpha$  between the first extension member 18 and the first arm member 12 to be selectively increased and decreased, increasing and decreasing the range

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of motion. In a first position **28**, the first extension member **18** is positioned at an angle  $\alpha_1$ , wherein the operative connection, at point "P," of the first and second extension members **18** and **20** is located in a plane "A" passing through the joint axis **16**, wherein plane "A" is substantially orthogonal to a longitudinal axis of the first arm member **12**. The first position **28** of point "P" provides a maximum angle of flexion of  $\beta_1$ . The second extension member stop **24** acts to limit the angle of maximum extension  $\gamma_1$  between the second arm member **14** and the joint axis **16**.

Referring to FIG. **5**, in a second position **30** the angle  $\alpha$  is increased to an angle  $\alpha_2$ , positioning the point "P" to a location "in front of" the plane "A." The second position **30** of point "P" provides a maximum angle of flexion of  $\beta_2$ , wherein  $\beta_2$  is greater than  $\beta_1$ . The second extension member stop **24** acts to limit the angle of maximum extension  $\beta_2$  between the second arm member **14** and the joint axis, wherein  $\gamma_2$  is less than the  $\gamma_1$ .

The selective pivotal connection **26** of the first extension member **18** to the first arm member **12** can have a plurality of selectable positions. The angle  $\alpha$  between the first arm member **12** and the first extension **18** can be selectively increased to move the point "P", on, "in front of" or "behind" the plane "A." It is also envisioned that a position can be selected to increase the angle  $\alpha$  between the first arm member **12** and the first extension **18** sufficiently to move the point "P" "in front of" plane "A" and "above" the longitudinal axis of the first arm member **12**, maximizing the maximum angle of flexion  $\beta$ .

The orthosis **10** of the present invention can be connected to the flexor side of the first and second body portions of the joint, which results in a decrease in angle as the joint is flexed (bent) and an increase in angle and the joint is extended (straightened). Alternatively, orthosis **10** of the present invention can be connected to the extensor side of the joint, which results in a decrease in angle as the joint is extended straightened and an increase in angle as the joint is flexed (bent).

The previous description of the first arm member **12** depicts a first extension **18** having a substantially linear shape, extending at an angle  $\alpha$  from the first arm member **12**. However, it is within the scope of the present invention that the first extension member **18** can be any shape extending from the first arm member **12** which positions the point "P" in the desired relationship to the plane "A." Referring to FIG. **6**, a segmented first extension member is shown, including a first extension member segment **18a** and a second extension member segment **18b**. The first and second extension member segments **18a** and **18b** extend from the first arm member **12**, positioning the point "P" at an angle  $\alpha$  from the first arm member **12**. Referring to FIG. **7**, an arcuate first extension member **18c** is shown. The arcuate extension member **18c** extends from the first arm member **12**, positioning the point "P" at an angle  $\alpha$  from the first arm member **12**.

Referring to FIG. **8**, the orthosis **10** of the present invention includes a first arm member **12** attachable to the first body portion and a second arm member **14** attachable to the second body portion, wherein the joint axis **16** is interposed between and offset from the first and second arm members **12** and **14**. The first and second arm members **12** and **14** are connected with each other offset from the joint axis **16**.

The first arm member **12** of the orthosis **10** includes a first extension member **18**, which extends at angle  $\alpha$  from the first arm member **12**. The second arm member **14** of the orthosis **10** includes a second extension member **20**, having an arcuate shape. The first and second extension members **18** and **20** are operatively connected a point "P," such that in operation the second extension member **20** travels along an arcuate path

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about and substantially through point "P." The arcuate shape of the second extension member **20** results in the second body portion rotating about the joint axis **16**, when the second arm member **14** is moved from a first position to a second position relative to the first arm member **12**. The angle  $\alpha$  between the first extension member **18** and the first arm member **12** and the radius of curvature of the second extension member **20** are a function of the joint to be treated and the degree of flexion or extension contractures.

A first cuff **32** is attached to the first arm member **12**, wherein the first cuff **32** is positionable about the first body portion. The first cuff **32** is attached to the first body portion by cuff straps. The first cuff **32** secures the first body portion to the first arm member **12**. A second cuff **34** is attached to the second arm member **14**, wherein the second cuff **34** is positionable about the second body portion. The second cuff **34** is attached to the second body portion by cuff straps. The second cuff **34** secures the second body portion to the second arm member **14**. (The term "cuff" as used herein means any suitable structure for transmitting the force of the orthosis **10** to the limb portion it engages.)

In an exemplary use, the orthosis **10** is operated to extend a joint in the following manner. The first cuff **32** is fastened about the first body portion tightly enough that the first arm member **12** may apply torque to the first body portion without having the first cuff **32** slide along the first body portion. Similarly, the second cuff **34** is fastened securely around the second body portion so that the second arm member **14** may apply torque to the second body portion without the second cuff **34** sliding along the second body portion. The orthosis **10** is attached to the first and second body portions in a first position. The second arm member **14** is rotated from the first position to a second position, relative to the first arm member **12**, rotating the second body portion about the joint axis **16** stretching the joint. As the second arm member **14** is rotated to the second position, the second extension member **20** travels along an arcuate path about and substantially through point "P." The orthosis **10** is maintained in the second position for a predetermined treatment time providing a constant stretch to the joint. After the expiration of the treatment time, the second arm member **14** is moved back to the first position, relieving the joint. Optionally, the second arm member **14** can be rotated to a third position, increasing the stretch on the joint. The second arm member **14** can be rotated at discrete time intervals to incrementally increase the stretch of the joint through the treatment cycle. After completion of the treatment cycle, the second arm member is returned to the first position for removal of the orthosis **10**.

The first and second arm members **12** and **14** are rigid members made of, for example, aluminum, stainless steel, polymeric, or composite materials. The arms are rigid so as to be able to transmit the necessary forces. It should be understood that any material of sufficient rigidity can be used.

In an embodiment, the components of the orthosis **10** of the present invention are made by injection molding. Generally for injection molding, tool and die metal molds of the orthosis **10** components are prepared. Hot, melted plastic material is injected into the molds. The plastic is allowed to cool, forming components. The components are removed from the molds and assembled. The cuff portions **32** or **34** can be individual molded and attached to the arm members **12** or **14**. Alternatively, the cuff portions can be molded as an integrated part of the arm members **12** or **14**.

In use, the orthosis **10** can be connected to the flexor side of the first and second body portions of the joint, which results in a decrease in angle as the joint is flexed (bent) and an increase in angle as the joint is extended (straightened). Alternatively,

orthosis **10** of the present invention can be connected to the extensor side of the joint, which results in a decrease in angle as the joint is extended straightened and an increase in angle as the joint is flexed (bent).

In an embodiment, the orthosis **10** includes a first cuff **32** for attachment to a first body portion, and a second cuff **34** for attachment to a second body portion. The first body portion is joined to the second body portion at a joint, around which is located, as is well known, soft tissue. Each of the first and second cuffs **32** and **34** includes loop connectors for receiving straps extending around the body portions to clamp the cuffs **32** and **34** to the body portions.

The first cuff **32** is mounted for sliding movement on the first arm member **12** and is slidable along the first arm member **12** in a manner as described below. The second cuff **34** is mounted for sliding movement on a second arm member **14** and is slidable along the second arm member **12** in a manner as described below.

#### Bending a Joint in Extension:

In operation of the orthosis **10** to extend the joint, the orthosis **10** starts at a more flexed position. The first and second cuffs **32** and **34** are clamped onto the first and second body portions, respectively, by straps, tightly enough so that the cuffs **32** and **34** can apply torque to the body portions to extend the joint. The second arm member **14** is rotated from the first position to a second position, relative to the first arm member **12**, rotating the second body portion about the joint axis **16** stretching the joint. As the second arm member **14** is rotated to the second position the second extension member **20** travels along an arcuate path about and substantially through point "P." The orthosis **10** is maintained in the second position for a predetermined treatment time providing a constant stretch to the joint.

As the orthosis **10** is rotated from the first position to the second position, extending the joint, the first and second cuffs **32** and **34** move along the first and second arm members **12** and **14**. The first cuff **32** moves inwardly along the first arm member **12**. Similarly, the second cuff **34** moves inwardly along the second arm member **14**. Because the cuffs **32** and **34** are clamped onto the first and second body portions as described above, the outward pivoting movement of the first and second arm members **12** and **14** and the cuffs **32** and **34** causes the joint to be extended as desired. However, this extension of the joint can place strong distractive forces on the soft tissues around the joint. The sliding movement of the cuffs **32** and **34**, inwardly along the first and second arm members **12** and **14**, helps to limit these distractive forces by counteracting the outward movement of the first and second arm members **12** and **14**. The cuffs **32** and **34** slide inwardly along the first and second arm members **12** and **14** a distance far enough so that the joint is only slightly distracted during extension. Thus, the detrimental effects of strong distractive forces normally generated in forced extension of a joint are avoided, being replaced with the beneficial effects of limited and controlled distraction.

#### Bending a Joint Flexion:

In operation of the orthosis **10** to flex the joint, the orthosis **10** starts at a more extended position. The first and second cuffs **32** and **34** are clamped onto the first and second body portions, respectively, by straps, tightly enough so that the cuffs **32** and **34** can apply torque to the body portions to extend the joint. The second arm member **14** is rotated from the first position to a second position, relative to the first arm member **12**, rotating the second body portion about the joint axis **16** stretching the joint. As the second arm member **14** is rotated to the second position the second extension member **20** travels about and substantially through point "P," along an

arcuate path. The orthosis **10** is maintained in the second position for a predetermined treatment time providing a constant stretch to the joint.

As the orthosis **10** is rotated from the first position to the second position, flexing the joint, the first and second cuffs **32** and **34** move along the first and second arm members **12** and **14**. The first cuff **32** moves outwardly along the first arm member **12**. Similarly, the second cuff **34** moves outwardly along the second arm member **14**. Because the cuffs **32** and **34** are clamped onto the first and second body portions the inward pivoting movement of the first and second arm members **12** and **14** and the cuffs **32** and **34** causes the joint to be flexed as desired. However, this flexion of the joint can place strong compressive forces on the soft tissues around the joint. The sliding movement of the cuffs **32** and **34**, outwardly along the first and second arm members **12** and **14**, helps to limit these compressive forces by counteracting the inward movement of the first and second arm members **12** and **14**. The cuffs **32** and **34** slide outwardly along the first and second arm members **12** and **14** a distance far enough so that the joint is only slightly compressed during flexion. Thus, the detrimental effects of strong compressive forces normally generated in forced flexion of a joint are avoided, being replaced with the beneficial effects of limited and controlled compression.

Referring now to FIG. 9, the orthosis **10** can be used to bend a wrist in flexion or extension. The orthosis **10** includes a first arm member **12** attachable to the forearm of a patient. The first cuff **32** is clamped onto the forearm by straps. A second arm member **14**, operatively connected to the first arm member **12**, is attachable to the hand of the patient, wherein the axis of the wrist joint is interposed between and offset from the first and second arm members **12** and **14**. The second arm member **14** includes a base member **36** attach thereto. A hand pad **38** is attached to the base member **36**. The hand pad **38** is clamped onto the hand by straps, tightly enough so that the second arm member **14** can apply torque to the joint. The hand pad **38** can be shaped to conform to the palm or the back surface of the hand.

#### Bending Wrist in Flexion:

When a wrist is to be bent in flexion, the first cuff **32** is connected with the forearm and the hand pad **38** is connected with the palm of the hand. The first cuff **32** and hand pad **38** are clamped onto the forearm and hand, respectively, by straps, tightly enough so that they can apply torque to flex the joint. The second arm member **14** is rotated from the first position to a second position, relative to the first arm member **12**, rotating the hand about the wrist joint axis **16** stretching the joint. As the second arm member **14** is rotated to the second position the second extension member **20** travels along an arcuate path about and substantially through point "P." The orthosis **10** is maintained in the second position for a predetermined treatment time providing a constant stretch to the wrist joint.

#### Bending Wrist in Extension:

When a wrist is to be bent in extension, the first cuff **32** is connected with the forearm and the hand pad **38** is connected with the back surface of the hand. The first cuff **32** and hand pad **38** are clamped onto the forearm and back surface of the hand, respectively, by straps, tightly enough so that they can apply torque to flex the joint. The second arm member **14** is rotated from the first position to a second position, relative to the first arm member **12**, rotating the hand about the wrist joint axis **16** stretching the joint. As the second arm member **14** is rotated to the second position the second extension member **20** travels along an arcuate path about and substantially through point "P." The orthosis **10** is maintained in the

second position for a predetermined treatment time providing a constant stretch to the wrist joint.

In an embodiment, the hand pad 38 is removable attached to the base member 36. The hand pad 38 includes a first surface, which has a substantially convex shape, to conform to the palm of the hand. A second surface, opposite the first surface, is also included, having a substantially concave shape, to conform to the back surface of the hand. The hand pad 38 can be removable attached to the base member 36 such that the first or second surfaces engages the hand of the patient.

For example, the hand pad 38 is removably secured to base member 36 by detent pin 40. The removable securing of the hand pad 38 allows the orthosis 10 to be used for both flexion and extension of the wrist. In flexion, the hand pad 38 is connected to the base member 36 with the first surface facing "up" to conform to the palm of the hand. In extension, the hand pad 38 is connected to the base member 36 with the second surface facing "up" to conform to the back surface of the hand.

The base member 38 can be mounted for sliding movement on the second arm member 14 and is slidable along the second arm member 14 in a manner as described below.

#### Bending Wrist in Extension:

In operation of the orthosis 10 to extend the wrist joint, the orthosis 10 starts at a more flexed position. The first cuff 32 is connected with the forearm and the hand pad 38 is connected with the palm of the hand. The first cuff 32 and hand pad 38 are clamped onto the forearm and palm of the hand so as to apply torque to extend the wrist joint. The second arm member 14 is rotated from the first position to a second position, relative to the first arm member 12, rotating the hand about the wrist joint axis 16 stretching the wrist joint. As the second arm member 14 is rotated to the second position the second extension member 20 travels along an arcuate path about and substantially through point "P." The orthosis 10 is maintained in the second position for a predetermined treatment time providing a constant stretch to the joint.

As the orthosis 10 is rotated from the first position to the second position, extending the joint, the base member 36 and hand pad 38 move along the second arm member 14. The base member 36 and hand pad 38 move inwardly along the second arm member 14. Because the cuff 32 and hand pad 38 are clamped onto the forearm and hand the outward pivoting movement of the first and second arm members 12 and 14 causes the joint to be extended as desired. However, this extension of the joint can place strong distractive forces on the soft tissues around the joint. The sliding movement of the base member 36 and hand pad 38, inwardly along the second arm member 14, helps to limit these distractive forces by counteracting the outward movement of the second arm members 12 and 14. The base member 36 and hand pad 38 slide inwardly along the second arm member 14 a distance far enough so that the joint is only slightly distracted during extension. Thus, the detrimental effects of strong distractive forces normally generated in forced extension of a joint are avoided, being replaced with the beneficial effects of limited and controlled distraction.

#### Bending Wrist in Flexion:

In operation of the orthosis 10 to flex the wrist joint, the orthosis 10 starts at a more extended position. The first cuff 32 is connected with the forearm and the hand pad 38 is connected with the back surface of the hand. The first cuff 32 and hand pad 38 are clamped onto the forearm and back surface of the hand so as to apply torque to flex the wrist joint. The second arm member 14 is rotated from the first position to a second position, relative to the first arm member 12, rotating

the hand about the wrist joint axis 16 stretching the wrist joint. As the second arm member 14 is rotated to the second position the second extension member 20 travels along an arcuate path about and substantially through point "P." The orthosis 10 is maintained in the second position for a predefined treatment time providing a constant stretch to the joint.

As the orthosis 10 is rotated from the first position to the second position, flexing the joint, the base member 36 and hand pad 38 move along the second arm member 14. The base member 36 and hand pad 38 move outwardly along the second arm member 14. Because the cuff 32 and hand pad 38 are clamped onto the forearm and hand the inward pivoting movement of the first and second arm members 12 and 14 causes the joint to be flexed as desired. However, this flexing of the joint can place strong compressive forces on the soft tissues around the joint. The sliding movement of the base member 36 and hand pad 38, outwardly along the second arm member 14, helps to limit these compressive forces by counteracting the inward movement of the first and second arm members 12 and 14. The base member 36 and hand pad 38 slide outwardly along the second arm member 14 a distance far enough so that the joint is only slightly compressed during extension. Thus, the detrimental effects of strong compressive forces normally generated in forced flexion of a joint are avoided, being replaced with the beneficial effects of limited and controlled compression.

In the above description, the hand pad 38 is shown sliding inwardly and outwardly along the second arm member 14. However, it is contemplated that the hand pad 38 can slide in other directions. For example, the hand pad 38 can slide substantially orthogonal to the second arm member 14, wherein the substantially orthogonal directions can have an arcuate path. Similarly, as discussed in more detail below, it is contemplated within the scope of the present invention that hand pad 38 can be connected to the second arm member 14 such that hand pad 38 can exhibit both longitudinal and orthogonal motion (and combinations thereof) with respect to the second arm member 14.

In the above description, the second extension member 20 is shown and described as having a substantially circular arcuate shape, positioning the axis of rotation at the joint axis 16. However, it is contemplated that the second extension member 20 can have alternative shapes.

Referring to FIG. 10, the second arm member 14 is shown having a non-circular arcuate shaped second extension member 44. The non-circular arcuate shaped second extension member 44 provide an axis of rotation which changes as the second arm member 14 is moved from the first position to the second position. As such, as the second arm member 14 is moved from the first position to the second position the second body portion will exhibit both a rotational motion, about the joint axis 16, and a translational motion, distracting or compressing the joint.

In the previously described embodiments, the arcuate shape of the second extension member 20 or 44 as shown have concave radius of curvature relative to the joint 16. However, referring to FIG. 11, it is contemplated that the second extension member 18 or 44 can have a convex radius of curvature relative to the joint 16. Similar to the concave radius of curvature, the convex arcuate shape of the second extension member 18 or 44 results in the second body portion rotating about the joint axis 16, when the second arm member 14 is moved from a first position to a second position relative to the first arm member 12.

Referring to FIG. 12, the second arm member 14 of the orthosis 10 includes a second extension member 48 extending therefrom and having a linear shape. The first and second

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extension members **18** and **48** are operatively connected at point "P." such that in operation the second extension member **48** travels along a linear path through point "P." The linear shape of the second extension member **48** results in the second body portion being translated with respect to the first body portion. The translational movement of the second arm member **14** results in a distraction or compression of the joint when the second arm member **14** is moved from a first position to a second position relative to the first arm member **12**.

As discussed further below, the hand pad can be mounted for translational and rotational movement on the base member.

#### Drive Assembly:

Referring to FIGS. **9** and **13A**, the drive assembly **22** of the orthosis includes a gear system. As previously noted, the components of the orthosis, including the drive assembly **22**, can be made by injection molding a polymer. The drive assembly **22** is supported in the first extension member **18**, including a gear **50** rotatable about point "P." A shaft **52**, attached to the gear **50**, extends from first extension member **18**. A knob **54** is connected to the shaft **52**, opposite the gear **50**, for manually rotating the gear **50**. The second extension member **20** includes a series of teeth **56** along an inner surface **58**. The second extension member **20** is threaded through the first extension member **18**, such that the teeth **56** on the second extension member **20** engage the gear **50**. The rotation of the knob **56** causes the gear **50** to rotate, pushing or pulling the second extension member **20** through the first extension member **18**. The drive assembly **22** includes a locking or breaking mechanism which prevents the gear **50** from rotating absent an applied force rotation of the knob **46**. Such a lock or breaking mechanism can include a compression washer or other known gear locking or breaking mechanisms.

In another embodiment, as shown in FIG. **13B**, the shaft **52** is attached to the gear **50** and extends from first extension member **18**. The knob **54** is connected to the shaft **52** opposite the gear **50** for manually rotating the gear **50**. The second extension member **20** includes a series of teeth **56** along an inner surface **58**. The teeth **56** can extend fully or partially along the width of the inner surface **58**. A secondary gear **51** is positioned between the gear **50** and the inner surface **58**, where the secondary gear **51** engages gear **50**. The second extension member **20** is threaded through the first extension member **18**, such that the teeth **56** on the second extension member **20** engage the secondary gear **51**. The rotation of the knob **56** causes the gear **50** to rotate, thereby rotating the secondary gear **51** and pushing or pulling the second extension member **20** through the first extension member **18**. The ratio between gear **50** and secondary gear **51** is selected to permit an easy rotation of the knob **54**, moving of the second extension member **20** through the first extension member **18**. The drive assembly **22** includes a locking or breaking mechanism which prevents the gear **50** from rotating absent an applied force rotation of the knob **46**. Such a lock or breaking mechanism can include a compression washer or other known gear locking or breaking mechanisms.

The drive assembly **22** is described as utilizing a gear system. However, it is contemplated that other known drive systems can be used to move the second extension member **20** through the first extension member **18**, for example a friction type drive system. Regardless of the drive system used, the joint orthosis of the present invention can act as a brace, restricting the relative movement of the first and second body portions to one degree of freedom (e.g. flexion and extension about the joint). Thus, drive assembly **22** can be configured to allow free motion in one degree of freedom. This can be

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achieved in a number of different ways. For example, gear **50** can be positioned such that it does not engage teeth **56**.

In an alternative embodiment, the drive assembly **22** for an orthosis **10** in accordance with the present invention can be actuated by a motor instead of by a manually actuatable member, such as the knob **54**.

In an embodiment, an electric motor is mounted to the shaft **52** for rotation of the gear **50**. A battery provides electric power to the motor. Alternatively, the motor can be supplied with external power. A microprocessor controls the operation of the motor. The microprocessor and motor together can be used to cycle the first and second arm members **12** and **14** through extension and flexion; to move the first and second arm members **12** and **14** in one pivotal direction a certain amount, hold there while tissue stretches, then move further in that direction; or in any other manner. In another manner of use, the orthosis can be set to cycle to one end of the joint's range of motion and hold there for a predetermined period of time, then cycle to the other end of the joint's range of motion and hold there. The programming and control of the microprocessor is within the skill of the art as it relates to driving the motor to control the first and second arm members **12** and **14** to move in known manners. This embodiment is ideally suited for continuous passive motion exercise, because the orthosis is portable and because the motor can be programmed with the desired sequence of movements.

It should be understood that the particular physical arrangement of the motor, the battery, and the microprocessor is not the only possible arrangement of those elements. The invention contemplates that other arrangements of these or similarly functional elements are quite suitable, and thus, the invention is intended to cover any such arrangement. Additionally, another type of power source, other than an electric motor, can also be used. For example, the use of a hydraulic or pneumatic motor as the drive mechanism is contemplated.

Referring to FIGS. **14** and **15**, another embodiment in which the hand pad **38** articulates with respect to the second arm member **14** is shown. The second arm member **14** has a circular base member **40** attached thereto. The circular base member **40** supports a circular base plate **42**. A circular cover **44** extends upwardly from the circular base member **40** and has a portion **46** extending radially inwardly toward a vertical axis **48** to define a slide chamber **50**.

A hand pad support slider **52** is received in the slide chamber **50**. The support slider **52** has an upper portion **54** to which the hand pad **38** is attached. The upper portion **54** is connected by a neck **56** to a circular planar portion **58**. Two annular bearing races **60** extend downwardly from the planar portion **58** and secure between them a plurality of ball bearings **62**. A washer **64** is disposed above the bearings **62**. The ball bearings **62** support the slider **52** and thus the hand pad **38** for sliding movement in any direction within the slide chamber **50**. The hand pad **38** can be made self-centering by springs **66**.

Thus, the hand pad **38** is slidable relative to the circular base member **40** in any direction for a limited extent. As indicated by the arrow **68**, the hand pad **38** is slidable fore and aft within the extent of travel allowed by the support slider **52** within the slide chamber **50**. As indicated by the arrow **70**, the hand pad **38** is slidable laterally within the extent of travel allowed by the support slider **52** within the slide chamber **50**. With these two combined, it can be seen that the roller bearing assembly provides a compound of movement of the hand pad **38**.

Referring to FIGS. **16**, **17A** and **17B**, another embodiment **80** in which the hand pad **38** articulates with respect to the second arm member **14** is shown. The second arm member **14** has a sliding base member **82** slidably mounted thereto in

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similar fashion to base member **36**. The sliding base member **82** supports a fixed base plate **84** attached thereto. A pivotal base plate **86** is pivotally connected to the fixed base plate **84**, where the pivotal base **86** plate can arcuately pivot with respect to the fixed base plate **84** and the second arm member **14**.

The pivotal base plate **86** is pivotally secured to the fixed base plate **84** by threaded members **88** and **90** extending through an arcuate slot **92** in the pivotal base plate **86**. The threaded members **88** and **90** are threaded in threaded holes **94** and **96** in the fixed plate **84**. In this manner the pivotal base plate **86** can travel along the arcuate slot **92** with respect to the fixed base plate **84**. The hand pad (not shown) can be removably attached to the pivotal base plate **86**.

In instances where a joint is misaligned, fixing the position of the joint can result in unwanted torsional forces being applied to the joint. The articulation of the hand pad permits the joint to self-align, such that the joint can be rotated about its axis without the application of torsional forces on the joint.

Referring now to FIG. **18**, an orthosis **100** can be used to bend a wrist in flexion or extension. The orthosis **100** includes a first arm member **102** attachable to the forearm of a patient. The first cuff **104** is clamped onto the forearm by straps **106**. A second arm member **108**, operatively connected to the first arm member **102**, is attachable to the hand of the patient, wherein the axis of the wrist joint is interposed between and offset from the first and second arm members **102** and **108**. The second arm member **108** includes articulating member **80** attached thereto. A hand pad can be attached to the pivotal base plate **86**. The hand is clamped onto the hand pad by top member **110** and strap **112**, tightly enough so that the second arm member **108** can apply torque to the joint. The hand pad can be shaped to conform to the palm or the back surface of the hand.

Referring to FIG. **19**, a hand pad **114** is provided, where the hand pad **114** can be removably attached to the pivotal base plate **86**. For example, a hook and loop tape **116** can be provided on the hand pad **114** and the pivotal base plate **86**. The hand pad **114** is shaped to conform to the palm of the hand.

Referring to FIG. **20**, another hand pad **118** is provided, where the hand pad **118** can be removably attached to the pivotal base plate **86**. Similarly, the hook and loop tape **116** can be provided on the hand pad **118** and the pivotal base plate **86**. The hand pad **118** is shaped to conform to a top surface of the hand.

Another embodiment of an orthosis of the present invention is in treatment of a toe of a patient's foot. While this embodiment is believed to provide significant improvements in this area of treatment, it may likewise be of benefit in treating other joints, such as ankles, knees, hips, fingers, wrists, elbows, shoulders, or the spine.

Furthermore, while many examples provided herein may illustrate the invention used to treat the metatarsal and proximal phalanx of the toe, these examples are non-limiting on other joints of the toe that also may be treated by the present invention. It is understood by those skilled in the art that the other joints of the toe may be flexed or extended, without departing from the spirit and scope of the invention. Additionally, the present invention is described in use on the "big" toe or hallux on the foot. Thus, it should be understood by those skilled in the art that the present invention is equally applicable for use on the second, third, fourth and minimus toes of the foot.

Each toe in the foot extends from the metatarsal bone and is formed by the proximal phalanx, middle phalanx, and distal phalanx, each of which is respectively pivotally connected to

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form a joint there between. The orthosis of the present invention may be configured to flex or extend (or both) a toe joint, where the joint defines an inner sector on the flexor side that decreases in angle as the joint is flexed (bent) and an outer sector on the extensor side that decreases in angle as the joint is extended (straightened).

Referring now to the figures in which like reference designators refer to like elements, there is shown in FIG. **21**, a schematic of the orthosis **200** of the present invention. The orthosis **200** includes a first member **202** attachable to a first body portion, such as a user's foot. The shape and configuration of the first member **202** may be selected to support or conform generally to a patient's foot. For example, the first member **202** may be a platform that contacts or supports the underside of a user's foot. Sidewalls or curved edges may be provided to help position, cradle, or securely hold the foot in proper position.

Alternatively, the first member **202** may have a profile or shape that generally conforms to a user's arch, shoe size, or foot width so that it fits more comfortably, holds the foot securely in place, or improves alignment of the device so that the range of motion imparted by the device corresponds to a joint's healthy range of motion. This conforming shape or profile may be accomplished, for instance, by providing interchangeable platforms corresponding to different foot sizes and shapes. The interchangeable platform may be selectively removed and replaced by an interchangeable platform of a different size. Alternatively, the first member **202** may have adjustable surfaces that can be resized or repositioned to better support or correspond to a patient's foot. For example, the overall length of the first member **202** may be adjustable, or the width of the first member **202** near the toes may be adjusted to account for different foot widths. In addition, raised walls or edges that support the feet may be selectively moveable so that they can be moved to accommodate different foot sizes. Once the foot is in place and the edges are moved to their desired position, they may be selectively locked or secured in place to help hold the foot in place. Additionally, the first member **202** may be configured with an arch, which in some instances also may be adjustable such as by having interchangeable arch inserts, by configuring the arch to be inflatable, or the like.

The first member **202** is operatively associated with or connected to a second member **204** so that the first and second members **202** and **204** may move or rotate with respect to each other. As shown in FIG. **21**, the supporting surface of the first member **202** may be offset from the supporting surface of the second member **204**. This amount of offset provided may vary from patient to patient or from joint to joint, and in some cases an offset may not be provided. Thus, it may be advantageous to allow the offset of the orthosis **200** to be adjustable so that a physician or user may change its size as needed to improve comfort, fit, or operation of the orthosis **200**.

In use, the second member **204** may be attachable to a second body portion, such as at least one toe on the foot so that the relative movement of the two members also causes movement of the joint. As shown in FIG. **22**, the orthosis **200** may have an axis of rotation **206** that is aligned with the axis of rotation of the joint. In this manner, the instantaneous axis of rotation (IAR) of the first and second members **202** and **204** may better match the IAR of the treated joint. As will be discussed in greater detail below, while the axis of rotation **206** of the device is illustrated in FIGS. **21-23** as occurring only along a single line, the axis of rotation **206** may also shift or move depending on the relative positioning of the first and second members **202** and **204** in a manner that corresponds to changing axis of rotation that a joint may experience through

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its range of motion. The first and second members **202** and **204** are operatively connected to each other, offset from the orthosis axis **206**.

The first member **202** of the orthosis **200** includes a first extension member **208** extending therefrom. The second member **204** of the orthosis **200** includes a second extension member **210** extending therefrom and having an arcuate shape. The first and second extension members **208** and **210** are operatively connected at point “P,” such that in operation the second extension member **210** travels along an arcuate path about and substantially through point “P.” The arcuate shape of the second extension member **210** results in the toe rotating about the orthosis axis **206**, or alternatively about a moving IAR, when the second member **204** is moved from a first position to a second position relative to the first member **202**.

The first extension member **208** can extend substantially vertically from the first member **12** or extend at an angle  $\alpha$  from the first member **202**. In one embodiment of the invention, the angle  $\alpha$  and the radius of curvature of the second extension member **210** are configured such that of the orthosis axis **206** is aligned with the axis of rotation of the joint. The previous description of the first member **202** depicts a first extension **208** having a substantially linear shape, extending at an angle  $\alpha$  from the first member **202**. However, it is within the scope of the present invention that the first extension member **208** can be any shape extending from the first member **202** which aligns orthosis axis **206** with the axis of rotation of the joint. Furthermore, as mentioned previously and again below, in some instances the axis of rotation of the joint may change or move slightly. Therefore, in some instances it may be desirable for the orthosis to mimic the IAR of the joint. As will be illustrated in detail below, this can be accomplished in several ways. One modification of the embodiment of the invention shown in FIG. **21**, for instance, may be for the second extension member **210** not to have a constant radius of curvature.

The orthosis **200** further includes a drive assembly **212**, which is illustrated in FIG. **21** at or near point “P.” In this embodiment, the drive assembly **212** is operably connected to the first and second extension members **208** and **210** for applying force to the first and second members **202** and **204** to pivot the second body portion about the orthosis axis **206**. As will be shown below in additional embodiments, the drive assembly **212** may be configured or disposed to interact with or operate on one of the first or second members **202** and **204** independently.

Referring to FIG. **22**, in order for the orthosis **200** to extend the joint the first and second members **202** and **204** may be affixed to the first and second body portions, respectively, tightly enough so that the first and second members **202** and **204** can apply torque to extend the joint.

The second extension member **210** is moved through the drive assembly **212** from a first position to a second position, relative to the first extension member **208**, rotating the second member **204** and the second body portion about the orthosis axis **206** stretching the joint. As the second member **204** is rotated to the second position, the second extension member **210** travels at least partially through point “P” and may travel substantially through this point for a large range of motion. Because the first and second members **202** and **204** are affixed to the first and second body portions, the outward pivoting movement of the second member **204** causes the joint to be extended as desired. The orthosis **200** may then be maintained in the second position for a predetermined treatment time providing a constant stretch to the joint. The orthosis may alternatively be configured to impart a constant force or load

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on the joint or may utilize the techniques of Static Progressive Stretch as described in co-pending application Ser. No. 11/203,516, entitled “Range of Motion System and Method”, and filed on Aug. 12, 2005, the entirety of which is incorporated by reference.

Returning to the example where the orthosis is maintained in the second position, after the expiration of the treatment time, the second member **204** may then be moved back to the first position, relieving the joint. Optionally, the second member **204** can be rotated to a third position, increasing the stretch on the joint, or partially reducing it to allow limited relaxation of the surrounding tissue. The second member **204** can be rotated at discrete time intervals to incrementally increase, reduce, or vary the stretch of the joint through the treatment cycle. After completion of the treatment cycle, the second arm **204** is returned to the first position for removal of the orthosis **200**.

Referring to FIG. **23**, in operation of the orthosis **200** to flex the joint. The first and second members **202** and **204** are affixed to the first and second body portions, respectively, tightly enough so that the first and second members **202** and **204** can apply torque to extend the joint. A cuff strap, laces, or other retaining device may be used to securely associate respective body portions of the joint with the first and second members **202**, **204**. The second extension member **210** is moved through the drive assembly **212** from the first position to a second position, relative to the first extension member **208**, rotating the second member **204** and the second body portion about the orthosis axis **206** stretching the joint. As the second member **204** is rotated to the second position, the second extension member **210** travels substantially through point “P.” Because the first and second members **202** and **204** are affixed to the first and second body portions, the inward pivoting movement of the second member **204** causes the joint to be flexed as desired. The orthosis **200** is maintained in the second position for a predetermined treatment time providing a constant stretch to the joint.

After the expiration of the treatment time, the second member **204** is moved back to the first position, relieving the joint. Optionally, the second member **204** can be rotated to a third position, thereby increasing, decreasing, or otherwise varying the stretch on the joint. The second member **204** can be rotated at discrete time intervals to incrementally increase the stretch of the joint through the treatment cycle. After completion of the treatment cycle, the second arm **204** is returned to the first position for removal of the orthosis **200**.

FIGS. **24-26** further illustrate several aspects of the invention more concretely. An orthosis **220** of the present invention includes a first member **221** having a first cuff **222** attachable to a user’s foot and a second member **223** having a second cuff **224** attachable to a toe of the user’s foot, wherein the second member **223** is rotatable with respect to the first member **221** about an axis of rotation **226**. The first and second members **221** and **223** are attached to the foot and toe of the user with the first and second cuffs **222** and **224**, such that as the second member **223** is rotated about the axis of rotation **226**, the toe is rotated about a joint axis.

A first extension member **228** is affixed to and extends from the first member **221**, wherein a drive assembly **230** is positioned on an end portion of the first extension member **228**. A second extension member **232** is similarly affixed to and extends from the second member **223**, wherein the second extension member **232** has an arcuate shape. The second extension member **232** engages the drive assembly **230** of the first extension member **228** at a point “P.” An actuation of the drive assembly **230** operates to move the second extension member **232** through the drive assembly **230**, such that the

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second cuff **224** travels along an arcuate path “A” with respect to the first member **221**. The arcuate shape of the second extension member **232** results in the toe rotating about the joint axis, as the second cuff **224** is moved along the arcuate path “A.” The drive assembly **230** can be actuated to move the second cuff **224** and toe from a first position to a second position relative to the first cuff **222**. Once again, the term “cuff” as used herein means any suitable structure for transmitting the force of the orthosis **220** to the limb portion it engages.

The first extension member **228** can extend substantially vertically from the first member **221** or extend at an angle  $\alpha$  from the first member **221**, where the angle  $\alpha$  and the radius of curvature of the second extension member **232** (if constant) can be configured such that of the axis of rotation **226** is aligned with the joint axis of rotation. As previously discussed, the curvature of the second extension member **232** need not be constant, and therefore the axis of rotation may shift or move in a manner that preferably mimics or approximates the moving IAR the joint would normally have. Another potential benefit of the orthosis **220** having the capability of a moving IAR is when multiple joints are being treated by the device. For instance, the range of motion of the tip of a toe or finger may involve cooperative motion of two or more joints. If the combined bending of the multiple joints causes the overall motion to rotation about a moving axis, it would be beneficial for the orthosis to approximate this moving IAR. Thus, the curvature of the second extension member **232** may be complex in order to better approximate a moving IAR.

Referring to FIG. 27, the drive assembly **230** can include a housing **240** having a worm gear **242** therein. A first miter gear **244** is attached to the worm gear **242** such that a rotation of the first miter gear **244** rotates the worm gear **242**. The drive assembly **230** further includes a drive shaft **246** have a knob **248** at one end and a second miter gear **250** at an opposite end. The second miter gear **250** is positioned within the housing **240**, in engagement with the first miter gear **244**. A rotation of the knob **248** rotates the drive shaft **246** and the second miter gear **250**, which in turn rotates the first miter gear **244** and the worm gear **242**.

A gear surface **252** of the second extension member **232** includes a plurality of teeth **254**. The second extension member **232** is positioned throughout the housing **240**, such that the worm gear **242** engages the teeth **254** of the second extension member **232**. A rotation of the knob **248** rotates the worm gear **242**, which in turn moves the second extension member **232** through the housing **240**.

In an alternative embodiment, the drive assembly **230** for orthosis **230** in accordance with the present invention can be actuated by a motor instead of by a manually actuatable member, such as the knob **248**. Likewise, the motor may be configured an adapted with gearing that causes the orthosis to cycle through a range of motion in a predetermined manner, or alternatively maybe controlled by a programmable logic controller (PLC).

In an embodiment, an electric motor is mounted to the drive shaft **246** for rotation of the second miter gear **250**. A battery or other source of energy provides electric power to the motor. Alternatively, the motor can be supplied with external power. A microprocessor controls the operation of the motor. The microprocessor and motor together can be used to cycle the second cuff **34** through a plurality of positions that cause the joint to undergo a range of motion, either by extension, by flexion, or both. For example, the microprocessor may be used to move the second cuff **34** in one pivotal direction a certain amount, hold there while tissue stretches, then move further in that direction; or in any other manner.

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In another manner of use, the orthosis can be set to cycle to one end of the joint's range of motion and hold there for a predetermined period of time, then cycle to the other end of the joint's range of motion and hold there. The programming and control of the microprocessor is within the skill of the art as it relates to driving the motor to control the second cuff **34** to move in known manners. This embodiment is ideally suited for continuous passive motion exercise, because the orthosis is portable and because the motor can be programmed with the desired sequence of movements.

It should be understood that the particular physical arrangement of the motor, the power source, and the microprocessor is not the only possible arrangement of those elements. The invention contemplates that other arrangements of these or similarly functional elements are quite suitable, and thus, the invention is intended to cover any such arrangement. Additionally, another type of power source, other than an electric motor, can also be used. For example, the use of a hydraulic or pneumatic motor as the drive mechanism is contemplated.

The present invention can further include a monitor for use with the orthosis **220**, which provides assurances the patient is properly using the orthosis **220** during his/her exercise period. For instance, the monitor can have a position sensor, a temperature sensor, a force sensor, a clock or timer, or a device type sensor for monitoring the patient's implementation of a protocol. The information obtained from these monitoring devices may be stored for later analysis or confirmation of proper use or may be transmitted in real-time during use of the device. The data obtained from the monitor can be analyzed by a healthcare professional or technician and the protocol can be adjusted accordingly.

This analysis may be conducted remotely, thereby saving the time and expense of a home visit by a healthcare professional or technician. An exemplary monitoring system is provided in U.S. Publication No. 20040215111 entitled “Patient Monitoring Apparatus and Method for Orthosis and Other Devices,” to Bonutti et al., the content of which is herein expressly incorporated by reference in its entirety.

In an exemplary use, the orthosis **220** is operated to rotate a toe about a joint axis in the following manner. The first cuff **222** is fastened about the foot with one or more straps, laces, or similar retaining device. Similarly, the second cuff **224** is fastened securely to the toe of the user, such that the joint and joint axis **226** is interposed between the first and second cuffs **222** and **224**. The orthosis **220** is attached to the foot and toe in a first position. The drive assembly **230** is actuated to move the second extension member **232**, such that the second cuff **224** travels along an arcuate path from the first position to a second position, relative to the first cuff **222**, rotating the toe about the joint axis stretching the joint. The orthosis **220** is maintained in the second position for a predetermined treatment time providing a constant stretch to the joint. After the expiration of the treatment time, the second cuff **224** is moved back to the first position, relieving the joint. Optionally, the second cuff **224** can be rotated to a third position, thereby increasing or decreasing the stretch on the joint. The second cuff **224** can be rotated at discrete time intervals to incrementally increase the stretch of the joint through the treatment cycle. After completion of the treatment cycle, the second arm member is returned to the first position for removal of the orthosis **220**.

Referring to FIG. 28, the second member **223** can include an attachment bracket **260** for adjustably attaching the second cuff **224** to the second extension member **232**. The attachment bracket **260** can include a toe rod **262** extending therefrom. The second cuff **224** can be slideably mounted on the toe rod

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262 to position second cuff 224 over the toe. Alternatively, the toe rod 262 can be of sufficient length such that the second cuff 24 can be slidably positioned on a selected toe on the foot of the user, for example, the big toe, minimus toe, or any toe therebetween.

The second cuff 224 can be positioned on the toe rod 262 with a first bracket 264, where the toe rod 262 passes through a passage 266 in the first bracket 264. A set screw 268 is provided to secure the first bracket 264 to the toe rod 262. When the set screw 268 is loosened, the first bracket 264 is free to slide along the toe rod 262. A tightening of the set screw 268 secures the first bracket 264 in place on the toe rod 272.

The second cuff 224 can further include a second bracket 270, where the second bracket 270 can be pivotally mounted to the first bracket 264. For example, the second bracket 270 can be attached to the first bracket 264 with a pin or screw connector, allowing the second bracket 270 to rotate with respect to the first bracket 264.

Additionally, when a joint is flexed or extended a compressive force may be applied to the connective tissue surrounding the joint. It may be desirable to control the compressive force, distracting the joint as the joint is flexed or extended. "Distraction" is defined by one dictionary as "Separation of the surfaces of a joint by extension without injury or dislocation of the parts." (Taber's Cyclopedic Medical Dictionary, 16th Edition, 1989, page 521), and involves stretching rather than compressing the joint capsule, soft tissue, ligaments, and tendons.

Additionally, the second bracket 270 can be slideably mounted to the first bracket 264. For example the second bracket 270 can be mounted to the first bracket 264 with a dovetail joint 272, allowing the second bracket 270 to slide with respect to the first bracket 264. The sliding movement of the second cuff 224 helps to limit the distractive or compressive forces which can be imparted on the joint by the rotation of the second cuff 224 with respect to the first cuff 222.

The attachment bracket 260 can be pivotally mounted to the second extension member 232. For example, the attachment bracket 260 can be attached to the second extension member 232 with a pin or screw connector 274, allowing the attachment bracket 260 to rotate with respect to the second extension member 232. The second extension member 232 further includes an extension bracket 276 having a slotted portion 278. A set screw 280 is positionable through the slotted portion 278, engaging the attachment bracket 260, such that the set screw 280 can be used to control the pivotal position of the attachment bracket 260 with respect to the second extension member 232.

The adjustable connection of the second cuff 224 to the attachment bracket 260 and the pivotal connection of the attachment bracket 260 to the second extension member 232 can be used to align the second cuff 224 with the toe. The alignment of the second cuff 224 on the toe can be used to substantially limit the force applied to the toe to that of a torque about the joint axis 226.

Bending a Joint in Extension:

In operation of the orthosis 220 to extend the joint, the orthosis starts at a more flexed position. The first and second cuffs 222 and 224 are clamped onto the foot and toe portions, respectively, by straps 234, tightly enough so that the first and second members 221 and 223 can apply torque to extend the joint. The second extension member 232 is moved through the drive assembly 230 from the first position to a second position, relative to the first extension member 228, rotating the second cuff 224 and the toe about the orthosis axis 226 stretching the joint. As the second cuff 224 is rotated to the

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second position the second extension member 232 travels along an arcuate path "A" about and substantially through point "P." The orthosis 220 is maintained in the second position for a predetermined treatment time providing a constant stretch to the joint.

As the orthosis 220 is rotated from the first position to the second position, extending the joint, the second cuff 224 moves along the first bracket 64. Because the first and second members 221 and 223 are clamped onto the foot and toe as described above, the outward pivoting movement of the second cuff 224 causes the joint to be extended as desired. However, this extension of the joint can place strong distractive forces on the soft tissues around the joint. The sliding movement of the second cuff 224 helps to limit these distractive forces by counteracting the outward movement. Thus, the detrimental effects of strong distractive forces normally generated in forced extension of a joint are avoided, being replaced with the beneficial effects of limited and controlled distraction.

Bending a Joint Flexion:

In operation of the orthosis 220 to flex the joint, the orthosis 220 starts at a more extended position. The first and second cuffs 222 and 224 are clamped onto the foot and toe portions, respectively, by straps 234, tightly enough so that the first and second members 221 and 223 can apply torque to extend the joint. The second extension member 232 is moved through the drive assembly 230 from the first position to a second position, relative to the first extension member 228, rotating the second cuff 224 and the toe about the orthosis axis 26 stretching the joint. As the second cuff 224 is rotated to the second position the second extension member 232 travels along an arcuate path "A" about and substantially through point "P." The orthosis 220 is maintained in the second position for a predetermined treatment time providing a constant stretch to the joint.

As the orthosis 220 is rotated from the first position to the second position, flexing the joint, the second cuff 224 moves along the first bracket 264. Because the first and second members 221 and 223 are clamped onto the foot and toe as described above, the inward pivoting movement of the second cuff 224 causes the joint to be flexed as desired. However, this flexion of the joint can place strong compressive forces on the soft tissues around the joint. The sliding movement of the second cuff 224 helps to limit these compressive forces by counteracting the inward movement. Thus, the detrimental effects of strong compressive forces normally generated in forced flexion of a joint are avoided, being replaced with the beneficial effects of limited and controlled compression.

Referring to FIG. 29, the drive assembly 230 can be adjustable mounted to the first extension member 228. The first extension member 228 includes a longitudinal slotted section 282. A threaded member 284 is positioned through the longitudinal slotted section 282, where the threaded member 284 is threaded into a threaded hole 286 in the drive assembly 230. The position of the drive assembly 230 is secured on the first extension member 228 by tightening the threaded member 284, compressing the first extension member 228 between the threaded member 284 and the drive assembly 230. The position of the drive assembly 230 can be adjusted by loosening the threaded member 284 and sliding the drive assembly 230 along the longitudinal slot 282. In this manner the position of the drive assembly 230 can be adjusted to align the axis of rotation 226 with the joint axis.

The drive assembly 220 can further include an indented portion 288. The indented portion 288 is sized to receive the first extension member 228 therein, such that the first extension member 228 slides through the indented portion 288 as

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the drive assembly 230 is moved along the first extension member 230. The indented portion 288 is configured to align the drive assembly 230 with respect to the first extension member 228. The indented portion 288 provides the further benefit of resisting a rotation of the drive assembly 230 with respect to the first extension member 228 when the orthosis 220 is in use.

Referring to FIG. 30, the drive assembly 230 can include a pair of indented portions 288 and 290, positioned on opposite sides on the drive assembly 230. As shown in FIG. 29, the first indented section 288 can be used to position the drive assembly 230 in an outer position on the orthosis 220, where the drive assembly 230 is positioned on an outside surface 292 of the first extension member 228.

Alternatively, as shown in FIG. 31, the second indented section 290 can be used to position the drive assembly 230 in an inner position on the orthosis 220, where the drive assembly 230 is positioned on an inner surface 294 of the first extension member 228. The threaded member 284 is positioned through the longitudinal slotted section 282, where the threaded member 284 is threaded into a second threaded hole 296 in the drive assembly 230.

In an embodiment, the first member 221 can be adjustable mounted to the first cuff 222, such that the position of the second cuff 224 can be adjusted to align the second cuff 224 with a toe of interest and the joint axis of the toe. In instances where the joint of a toe is misaligned, for example for toe deformations such as hammer toe, bunion, etc., the linear and angular position of the second cuff 224 can be adjusted with respect to the first cuff 222 aligning the second cuff 224 with the misaligned toe such that the axis of rotation 226 of the orthosis 220 is aligned with the axis of rotation of the toe joint. In the manner, the orthosis 220 can be adjusted to prevent the unwanted application of torsional forces to the toe joint.

Referring to FIG. 32, the first member 221 is adjustably attached to a bottom surface of the first cuff 222. The first member 221 can include a longitudinal slot 300, through which a pair of threaded members 302 and 304 are positioned, attaching the first member 221 to the first cuff 222. The first member 221 can be moved along the longitudinal slot 300 to laterally adjust the position of the first member 221 with respect to the first cuff 222. The first member 221 is secured in position by tightening the threaded member 302 and 304, compressing the first member 221 between the threaded members 302 and 304 and the bottom surface 298 of the first cuff 222.

The first member 221 can further include a second longitudinal slot 306, parallel and offset from the first longitudinal slot 300. The first member 221 can be attached to the first cuff 222, using the second longitudinal slot 306 to longitudinally adjust the position of the first member 221 with respect to the first cuff 222. Similarly, the first member 221 can be moved along the second longitudinal slot 306 to laterally adjust the position of the first member 221 with respect to the first cuff 222.

It is also contemplated that the angular position of the first member 221 can be adjusted with respect to the first cuff 222. In an embodiment, as shown in FIG. 33, the bottom surface 298 of the first cuff 222 includes a center threaded hole 308 and an arcuate slot 310. An internally threaded fastener 312 is slidably positioned in the arcuate slot 310, opposite the bottom surface 298. The first member 221 is attached to the first cuff 222 by positioning the threaded members 302 and 304 through a longitudinal slot 300 or 306 of the first member 221 and engaging the threaded hole 308 and the internally threaded fastener 312 in the arcuate slot 310. The angular position of the first member 221 can be adjusted with respect

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to the first cuff 222 by pivoting the first member 221 about threaded member 302 in the center threaded hole 308, such that the internally threaded fastener 312 and the second threaded member 302 travel along the arcuate slot 310. The first member 221 is secured in position by tightening the threaded members 302 and 304, compressing the first member 221 between the threaded members 302 and the bottom surface 298 of the first cuff 222, and compressing the first member 221 and first cuff 222 between threaded member 304 and internally threaded fastener 312.

The bottom surface 298 of the first cuff 222 can further include a second arcuate slot 314, where an internally threaded fastener 316 is slidably positioned in the second arcuate slot 314, opposite the bottom surface 298 of the first cuff 222. Similar to arcuate slot 310, second arcuate slot 314 can be used to angularly adjust the position of the first member 221 with respect to the first cuff 222.

Specifically, the first member 221 is attached to the first cuff 222 by positioning the threaded members 302 and 304 through a longitudinal slot 300 or 306 of the first member 221 and engaging the threaded hole 308 and the internally threaded fastener 316 in arcuate slot 314. The angular position of the first member 221 can be adjusted with respect to the first cuff 222 by pivoting the first member 221 about threaded member 302 in the center threaded hole 308, such that the internally threaded fastener 316 and the second threaded member 304 travel along the arcuate slot 314. The first member 221 is secured in position by tightening the threaded member 302 and 304, compressing the first member 221 between the threaded members 302 and the bottom surface 298 of the first cuff 222, and compressing the first member 221 and first cuff 222 between the threaded member 304 and internally threaded fastener 316.

It is also contemplated that the first member 221 can be attached to the first cuff 221 using the arcuate slots 310 and 314 and the respected internally threaded members 312 and 316. Specifically, the first member 221 is attached to the first cuff 222 by positioning the threaded members 302 and 304 through a longitudinal slot 300 or 306 of the first member 221 and engaging the internally threaded fastener 312 in the arcuate slot 310 and the internally threaded fastener 316 in arcuate slot 314. The angular position of the first member 221 can be adjusted with respect to the first cuff 222 by pivoting the first member 221 such that the internally threaded fasteners 312 and 316 travel along the arcuate slots 310 and 314. The first member 221 is secured in position by tightening the threaded member 302 and 304, the first member 221 and first cuff 222 between the threaded members 302 and 304 and internally threaded fastener 312 and 316.

While the embodiment discussed above utilize a second extension member having an arcuate shape to control movement of the second member relative to the first, it should be understood that skilled artisans having the benefit of this disclosure will appreciate that other configurations may likewise provide similar relative movement.

FIG. 34, for example, schematically illustrates an embodiment of an orthosis 330 of the invention having a first member 332 and a second member 334, both of which preferably having sufficient structure or component parts to hold body members near the treated joint or joints. In the embodiment illustrated in FIG. 34 the second member has a first pivoting contact point 336 about which the geared body member may rotate. In this embodiment, the first pivoting contact 336 does not move in relation to the first body member 330, but as indicated in FIG. 32 one alternative embodiment may allow

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relative movement that can be resisted by a flexible device **338** such as a spring, compressed gas, foamed material, elastomer or the like.

Returning once again to FIG. **34**, the second member may have an additional pivot contact **340**, preferably disposed at a location at or near the opposite end of the second member **334** from where the first pivoting contact **336** is located. The second pivoting contact **340** may be configured with a drive assembly **344** that causes the second member **334** to follow a predetermined path. Thus, the second pivoting contact **340** in the embodiment of FIG. **34** is configured to move relative to the first member **332** in order to cause the joint to move from a first position to second one.

The drive assembly **344** illustrated in FIG. **34** is an arm or linkage **346** connected between the second pivot connection **340** and a rotating wheel **348**. The wheel **348** may be configured so that the linkage **346** can be selectively connected to it in different radial distances from the center of rotation of the wheel. This allows the range of motion to be adjustable by the care provider, physician, or patient. As the wheel **348** is rotated, the linkage **346** moves in a manner that causes the second member **334** to move in a particular way.

The second member **334** (or alternatively the first member **332**) may also have a sliding contact surface **342**. The sliding contact surface **342** allows the joint to rotate or move according to its natural instantaneous axis of rotation. Thus, if the second pivot contact **340** moves in a manner that does not always exactly correspond to the axis of rotation of the joint, the sliding contact surface **342** may move or adjust accordingly. Another potential advantage of the sliding contact surface **342** is that it may help facilitate proper alignment of the joint in the orthosis during initial setup.

FIG. **34** illustrates some variations that may also be used in orthosis of the invention. For instance, the first and/or second pivot contact may be configured with a cushion or spring **338** that allows one or both ends of the second member to impart some flexibility in the force imparted to the joint. As noted above, the cushion or spring **338** may be made of a variety of suitable materials and constructions to permit some flexibility in the movement of the pivot points **336**, **340**.

The use of a spring or cushion allows the orthosis **330** to be used in different treatment protocols than just by holding the joint in a prescribed location for a period of time. Instead, the orthosis can utilize the principles of static progressive stretch as described in copending application Ser. No. 11/203,516, entitled "Range of Motion System and Method", and filed on Aug. 12, 2005, the entirety of which is incorporated by reference.

Thus, an orthosis **330** configured with a spring or cushion **338** can be moved from an initial position to a second position that is determined not by position of the joint but instead by the amount of force the orthosis **330** imparts on the joint. The joint may then be subjected to this loading, and over time as the surrounding tissue stretches the joint will move and the imparted forces will be reduced. It should be noted that while FIG. **35** illustrates the cushion or spring **338** associated with the first pivot contact **336**, it is not required to be associated with it. Instead, for example, the cushion or spring **338** may be associated with the second pivot **340** so that it can flex or move in response to resistive forces of the joint and nearby tissue. Likewise, there may be a spring or cushion **338** associated with both pivot contacts **336**, **340**.

Another notable variation between the embodiments of FIGS. **34** and **35** is that the rotating wheel **348** in FIG. **34** has multiple single point connections for connecting the linkage **346** at different distances from the center of rotation of the wheel. In contrast, the embodiment of FIG. **35** illustrates that

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an elongated slot **350** may be used to connect the linkage **346**. The advantage of utilizing multiple single point connections may be ease of use and the ability to quickly confirm the orthosis **330** is properly configured for a prescribed treatment protocol, whereas one potential advantage of utilizing an elongated slot **350** is the ability to quickly adjust the settings without disassembling the device.

FIG. **36** illustrates an embodiment of the invention where the rotating wheel **348** is a cam surface **352**. This embodiment is similar to the use of cams and followers as described in U.S. Pat. No. 5,514,143, which is incorporated herein in its entirety. As shown, the cam surface **352** may have varying distance from the center of rotation of the wheel **348**. If the wheel **358** is circular, for example, the center of rotation may be located somewhere different from the geometric center of the circle or at the center of rotation of the shape. As it rotates, the circumferential outer surface causes the linkage **346** to move to the second member **340** in a desired manner. Additionally, the outer edge of the "wheel" **348** need not be round, but instead may be a cam surface **352** of varying distance from the center or rotation. Likewise, the outer surface may have varying radii of curvature as shown in FIG. **36**.

The embodiments of FIGS. **37** and **38** further illustrate that a cam surface **352** may be used to move the second member **332** in a desired, perhaps complex way. As is the case for other embodiments described herein, performance of the cam surface **352** may be enhanced because of the ability to better mimic or replicate a moving axis of rotation of the treated tissue and joint.

In FIG. **37**, the cam surface **352** is associated with the first member **332**. Linkages or arms **346** of the second member **334** have cam followers **354** that trace the cam surface **352** and cause the second member **334** to move in a more complex manner than just by rotation around a fixed axis.

The cam surface **352** of FIG. **37** also is associated with a slot **356** that allows the relative location of the first and second members **332** and **334** to be adjusted or moved without decoupling the cam followers **354** from the cam surface **352**. As shown, the slot **356** allows for horizontal adjustment repositioning. Although not shown, vertical slots may also be provided, either alone or in combination with a horizontal slot.

FIG. **38** illustrates an example where the linkage **346** is a cam surface **352** that passes through two or more points **358**, **360** that are stationary or fixed relative to the first member **332** when the orthosis **330** is in use (i.e. after alignment is completed). Once again, this embodiment may be configured to permit horizontal adjustment, such as by providing slot **368**, and likewise may be configured to be vertically adjustable. In addition, this embodiment also illustrates that the first and second members **332** and **334** may be represented by rotation about a pivot **370**. Thus, the use of horizontal, vertical, and rotational adjustment of the relative positions of the first and second members **332** and **334** may allow greater fitting of the orthosis **330** to the treated tissue and joint.

FIG. **39** is an exploded view of how the cam surface **352** and cam followers **354** may utilize a geared surface **372**. Utilizing a geared surface **372** may allow for a drive assembly **344** to automate the movement of the orthosis **330**.

FIGS. **40** and **41** schematically illustrate other ways in which potentially complex movement of the second member **334** may be controlled. FIG. **40** illustrates that the cam surface may not be directly formed from a component part of either the first or second members, but instead may be associated with some other structure. For instance, the orthosis **330** may be operatively connected to a base unit **374** having a plurality of cam surfaces **376** corresponding to different ranges of motion for related joints, such as when the orthosis **330** can be

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used to treat a plurality of different toes or a patient. Once the orthosis **181** is placed on the patient, the second member **334** will be positioned to securely hold one of the toes on the patient's foot and to engage with the cam surface **376** corresponding to that toe.

FIG. **41** shows that multiple cam surfaces or slots **378** may be formed in a side panel **380**. The side panel **380** may have a sliding engagement of the second member **334**. As the second member **334** moves, the engagement with the side panel **380** controls position and movement. Moreover, one or more sides or edges of a slot **316** of the embodiment of FIG. **41** may be geared to allow implementation of a drive assembly **344**.

FIG. **42** illustrates an embodiment where movement of at least part of a linkage **346** may be linear, but when combined with a rotational pivot **382**, sliding slot **384**, and possibly other components or combinations described herein, the net effect on the second member **334** is once again a controlled movement in a desired manner.

The components of the present invention are rigid members made of, for example, aluminum, stainless steel, polymeric, or composite materials. The member and extensions are sufficiently rigid to transmit the necessary forces. It should be understood that any material of sufficient rigidity might be used. For example, some components can be made by injection molding. Generally, for injection molding, tool and die metal molds of the components are prepared. Hot, melted plastic material is injected into the molds. The plastic is allowed to cool, forming components. The components are removed from the molds and assembled.

Furthermore, it is contemplated that the components can be made of polymeric or composite materials such that the device can be disposable. For example, at least some or all of the components can be made of a biodegradable material such as a biodegradable polymer. Among the important properties of these polymers are their tendency to depolymerize relatively easily and their ability to form environmentally benign byproducts when degraded or depolymerized. One such biodegradable material is poly (hydroxyacids) ("PHA's") such as polylactic acid ("PLA") and polyglycolic acid ("PGA").

Additionally, the device can be made of a nonmagnetic material. In such instance, the device can be used as a positioning device for use in imaging devices, such as a MRI device. It is also contemplated that the device can be used as a positioning device for use during surgical procedures, where it may be necessary to adjust and hold the position of the joint.

In a method of manufacture, the cuffs can include a base plate having a plurality a strap attached thereto, where the straps are position about a body portion of a patient. The straps are attached to the base plate using fastener elements, such as screws threaded into the base plate. The screws can be removable to allow for easy removal and/or replacement of the straps.

Alternatively, in an embodiment where the base plate is made of a polymeric material, the straps can be welded to the base plate using an energy welding technique such as, RF welding, ultra-sonic welding, high frequency welding, etc. For example, in ultra-sonic welding an acoustic tool is used to transfer vibrational energy into the weld areas of the straps and the base plate. The friction of the vibrating molecules generates heat, which melts the surface material of the base plate in the welding area, at which point the vibrational energy is stopped. Pressure is applied to the strap and the base plate, allowing the melted material to solidify within the material of the strap. In this method the strap is secured to the base plate without the need of fasteners.

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Similarly, where the cuffs are made of a polymeric material, the cuff can be welded to the orthosis using energy welding techniques. For example, the cuffs can be made of a substantially rigid, flexible, or fabric polymeric material which can be welded directly onto the arm members of the orthosis. It is also contemplated that the straps can be an integral part of the cuffs. For example, where the cuffs are made of a polymeric fabric, the straps can be integrally formed in the fabric pattern when making the cuffs.

All references cited herein are expressly incorporated by reference in their entirety.

It will be appreciated by persons skilled in the art that the present invention is not limited to what has been particularly shown and described herein above. For example, although the examples presented identify the toe joint, the present invention can be used for any joint in the body of the patient. In addition, unless mention was made above to the contrary, it should be noted that not all of the accompanying drawings are to scale. A variety of modifications and variations are possible in light of the above teachings without departing from the scope and spirit of the invention, which is limited only by the following claims.

What is claimed:

1. A device for moving a knee joint in a body of a patient, the device comprising:

a first arm member coupled to a first leg support configured to support an upper portion of a leg of the patient;

a second arm member coupled to a second leg support configured to support at least one of a lower portion of a leg and a foot of the patient;

a control assembly operatively connected to the first and second arm members and configured to selectively move the second arm member relative to the first arm member, the control assembly comprising:

a first motorized drive assembly coupled to the first and second arm members and operable to drive movement of the second arm member relative to the first arm member; and

a second motorized drive assembly coupled to the first and second arm members and operable to drive movement of the second arm member relative to the first arm member.

2. The device for moving a knee joint in a body of a patient as set forth in claim 1, wherein the first and second motorized drive assemblies include at least one of a hydraulic and pneumatic motor.

3. The device for moving a knee joint in a body of a patient as set forth in claim 1, further comprising a monitor having a storage medium, the monitor configured to track and store usage information of the device.

4. The device for moving a knee joint in a body of a patient as set forth in claim 3, wherein the monitor further comprises a display for displaying positional information of the device.

5. The device for moving a knee joint in a body of a patient as set forth in claim 3, wherein the monitor further comprises a data transfer component for wirelessly transferring usage information of the device.

6. The device for moving a knee joint in a body of a patient as set forth in claim 1, further comprising a locking mechanism configured to prevent actuation of at least one of the first motorized drive assembly and the second motorized drive assembly.

7. The device for moving a knee joint in a body of a patient as set forth in claim 1, further comprising a lower leg strap for securing at least one of the lower portion of a leg and the foot of the patient to the second leg support.

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8. The device for moving a knee joint in a body of a patient as set forth in claim 1, further comprising an upper leg strap for securing an upper portion of a leg of the patient to the first leg support.

9. The device for moving a knee joint in a body of a patient as set forth in claim 1, further comprising a timer.

10. The device for moving a knee joint in a body of a patient as set forth in claim 1, wherein the second drive assembly is configured to move the second arm member to at least one of increase and decrease a force exerted by the device.

11. The device for moving a knee joint in a body of a patient as set forth in claim 1, wherein the first motorized drive assembly includes a drive element configured to selectively move the second arm member while the second motorized drive assembly is maintained in a fixed position relative to the first and second arm members.

12. The device for moving a knee joint in a body of a patient as set forth in claim 1, wherein the second motorized drive assembly includes a drive element configured to selectively move the second arm member while the first motorized drive assembly is maintained in a fixed position relative to the first and second arm members.

13. The device for moving a knee joint in a body of a patient as set forth in claim 1 wherein the second arm member further comprises a telescoping member for adjusting the length of the second arm member.

14. A device for moving a leg of a user into flexion and extension, the device comprising:

a base member;

a first arm member coupled to the base member;

a second arm member coupled the first arm member;

a motorized drive assembly mounted to the base member and pivotably coupled to the second arm member, the drive assembly configured to selectively move the second arm member relative to the first arm member;

a motorized force application assembly coupled to the first arm member, the motorized force application assembly configured to control a force exerted by the device; and a locking mechanism coupled to at least one of the first and second arm members, the locking mechanism configured to prevent actuation of the first motorized drive assembly.

15. The device for moving a leg of a user into flexion and extension as set forth in claim 14, wherein the first arm member is coupled to a first leg support configured to support an upper portion of the leg and the second arm member is coupled to a second leg support configured to support at least one of a lower portion of the leg and a foot.

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16. The device for moving a leg of a user into flexion and extension as set forth in claim 14, further comprising a controller configured to enable a user to selectively move the second arm member to allow for angle control of the first and second arm members.

17. The device for moving a leg of a user into flexion and extension as set forth in claim 14, wherein the drive assembly enables incremental movement of the device to move the leg of a user.

18. The device for moving a leg of a user into flexion and extension as set forth in claim 17, wherein the monitor further comprises a data transfer component for wirelessly transferring usage information of the device.

19. The device for moving a leg of a user into flexion and extension as set forth in claim 17, wherein the monitor further comprises a display for displaying degrees of at least one of flexion and extension.

20. The device for moving a leg of a user into flexion and extension as set forth in claim 14, further comprising a monitor having a storage medium, the monitor configured to track and store usage information of the device.

21. The device for moving a leg of a user into flexion and extension as set forth in claim 14, wherein the motorized drive assembly includes at least one of a hydraulic and pneumatic motor.

22. The device for moving a leg of a user into flexion and extension as set forth in claim 14, further comprising at least one position sensor for monitoring the relative positional degrees of the first and second arm members.

23. A method for moving a leg of a user using a device, the method comprising:

securing a portion of an upper leg to a first leg support that is coupled to a first arm member;

securing at least one of a lower portion of a leg and a foot to a second leg support that is coupled to a second arm member that is coupled to the first arm member; and

operating a controller coupled to a motorized drive assembly and a motorized force application assembly configured to enable a user to selectively move the second arm member from a first position relative to the first arm member to a second position relative to the first arm member.

24. A method for moving a leg of a user using a device as set forth in claim 23, further comprising positioning a locking mechanism coupled to at least one of the first and second arm members such that the locking mechanism prevents the second arm member from moving past a second position relative to the first arm member.

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